A Practical Model for Hair Interaction

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Introduction

- Produce realistic looking hair
- Dynamics of long hair is difficult
 - High number of hair strands
 - 1 Complex physical interactions

Outline

- Hair modeling
- Single hair strand dynamics
- A sparse model for hair-hair interaction
 - Static links
 - Dynamic interactions
- Create dense hair with interpolation
- ; Hair rendering
- Demos

Hair modeling

- Few hundred strands à guide hair
- Each strand has multiple segments connected by vertices
- Structural elements added
 - Connections between vertices
 - Triangular meshes among guide hair

Hair modeling

Previous publication

<u>Modeling realistic virtual hairstyles -Y.Yu</u>









Single hair strand dynamics

- Rigid multi-body chain
- Rotational joint between segments
- à simple articulated body
- Forward dynamics solved using
 - Lagrange's equations
 - Articulated-Body method (linear time)

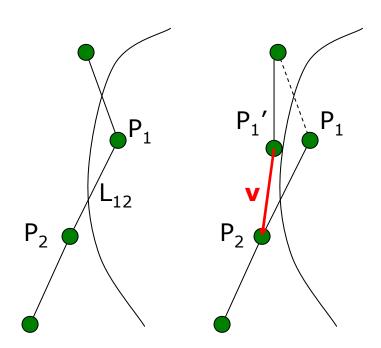
Strand-Object collision

- Hair vertex too close from object
- Set its velocity to the velocity of the object
- Check penetration of hair strand particles with the triangle mesh of the objects

Strand-Object collision

If penetration occurs

- We need to move vertex out
- We also move remaining part of strand



$$p_2' = p_1' + v'$$
 $v' = L_{21} \frac{v}{\|v\|}$

Repeat until we reach tip of strand

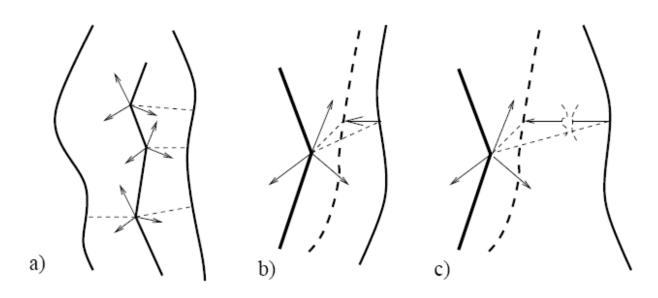
Hair-Hair interaction

Static links

- For hairs bonding effect
- Simulate the elastic lateral motion and enable hairstyle recovery
- 1 Hair à elastically deformable volume
- Links = breakable connections
- Links = springs with zero resting length
- Each segment connected to n closest neighbors

Static Links

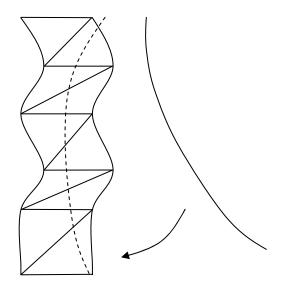
$$\mathbf{f}_h = \sum_{i} \left[k_{h,i}^s |\mathbf{l}_i| - k^d \frac{\mathbf{v}_i \cdot \mathbf{l}_i}{|\mathbf{l}_i|} \right] \frac{\mathbf{l}_i}{|\mathbf{l}_i|}$$

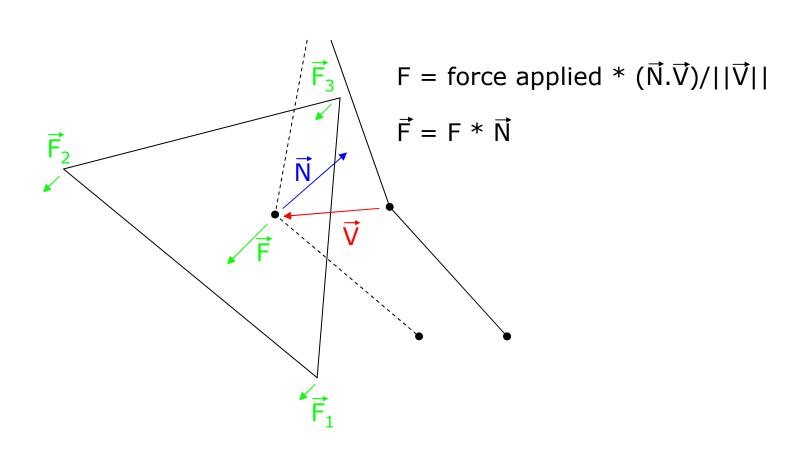


- Two objects in dynamic interactions: hair segments and triangle strips.
- Build triangle strips between guide hairs with adjacent roots.
- Place these in an octree or kd-tree for speed.

- Detect collisions: hair vertextriangle face and hair segment-hair segment.
- collisions occur when the two geometries are less than a threshold distance apart.
- Forces result from collision: spring force and friction. Forces on triangle are distributed to vertices.

- Dynamic interaction
 - Use triangle strip between hairs
 - Allowed when hairs have nearby roots
 - Triangle patches used for collision





Friction:

$$\mathbf{F}_{fric} = -\mu \mathbf{F}_{N} \frac{\mathbf{v}_{\text{rel, in plane}}}{\|\mathbf{v}_{\text{rel, in plane}}\|}$$

Plane determined by two segments, or face.

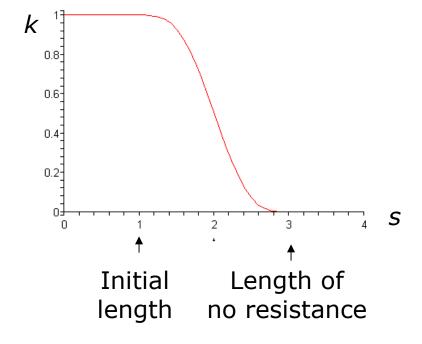
Term goes to zero as hairs line up.

$$\mathbf{F}_{s} = kd_{a,b} (1 - \left| \mathbf{T}_{a} \cdot \mathbf{T}_{b} \right|)$$

distance

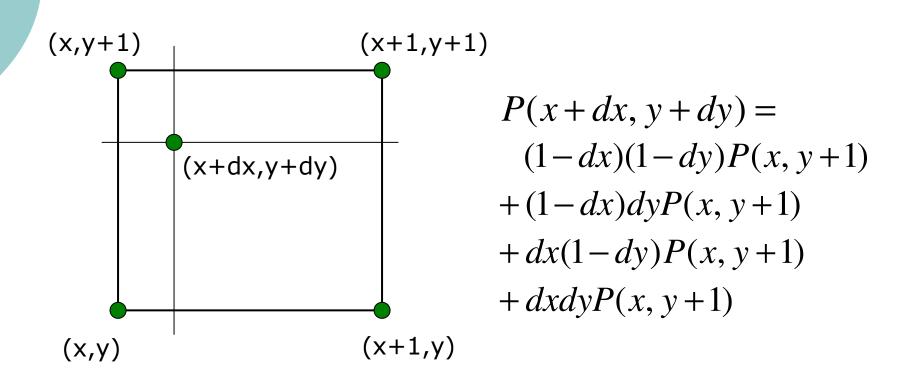
Segment-segment Tangent vectors for hair, or vertex-face computed in triangle by e.g. u direction.

- For vertex-face collisions, spring constant is a function of hair density on face.
- One solution: k a function of "horizontal" triangle edge length s:



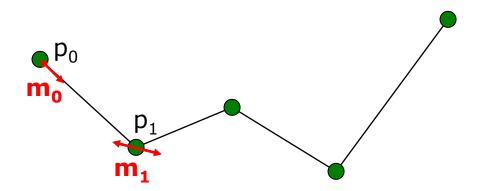
- Each hair from sparse model serves as a guide hair
- Remaining hair strands in dense set are interpolated from these guide hairs

Bilinear interpolation between guide hairs



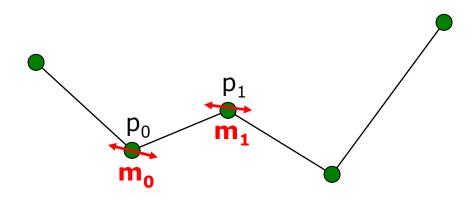
- Hermite Spline interpolation
 - Improve smoothness of strands
 - Only 10 to 15 segments are enough to have a smooth output

$$p(t) = (2t^3 - 3t^2 + 1)p_0 + (t^3 - 2t^2 + t)m_0 + (-2t^3 + 3t^2)p_1 + (t^3 - t^2)m_1$$



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