

Subdivision Surfaces

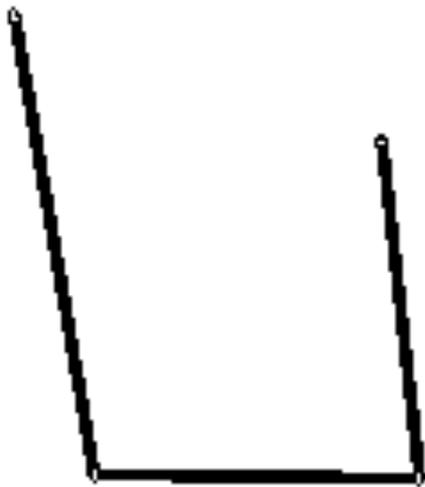
Connelly Barnes

CS 4810: Graphics

Acknowledgment: slides by Jason Lawrence, Misha Kazhdan, Allison Klein, Tom Funkhouser, Adam Finkelstein and David Dobkin

Subdivision

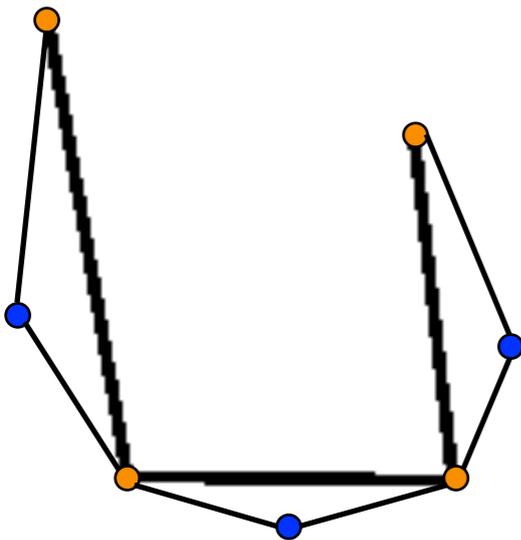
- How do you make a smooth curve?



We want to “smooth out” severe angles

Subdivision

- How do you make a smooth curve?



We want to “smooth out” severe angles

Subdivision

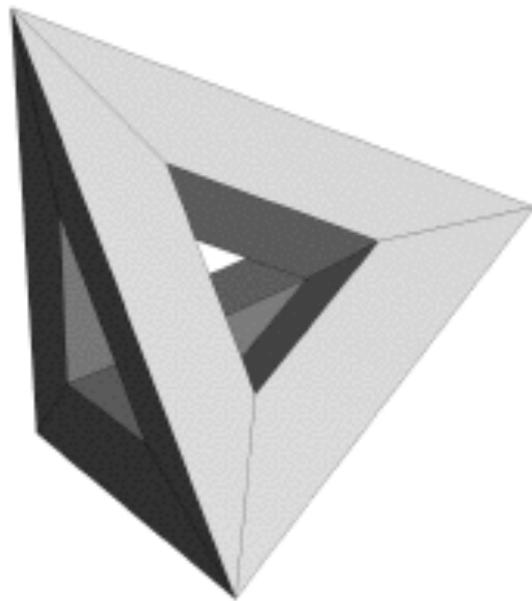
- How do you make a smooth curve?



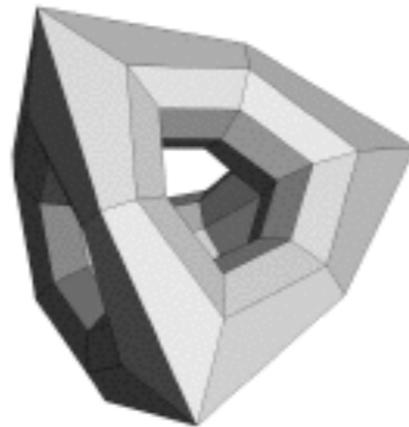
We want to “smooth out” severe angles

Subdivision Surfaces

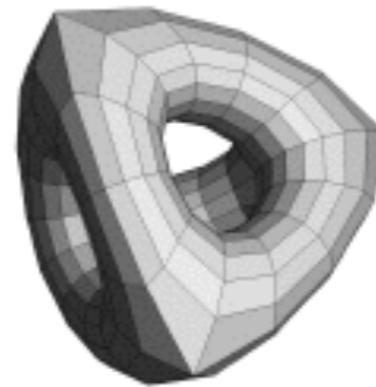
- Coarse mesh & subdivision rule
 - Define smooth surface as limit of sequence of refinements



(a)



(b)



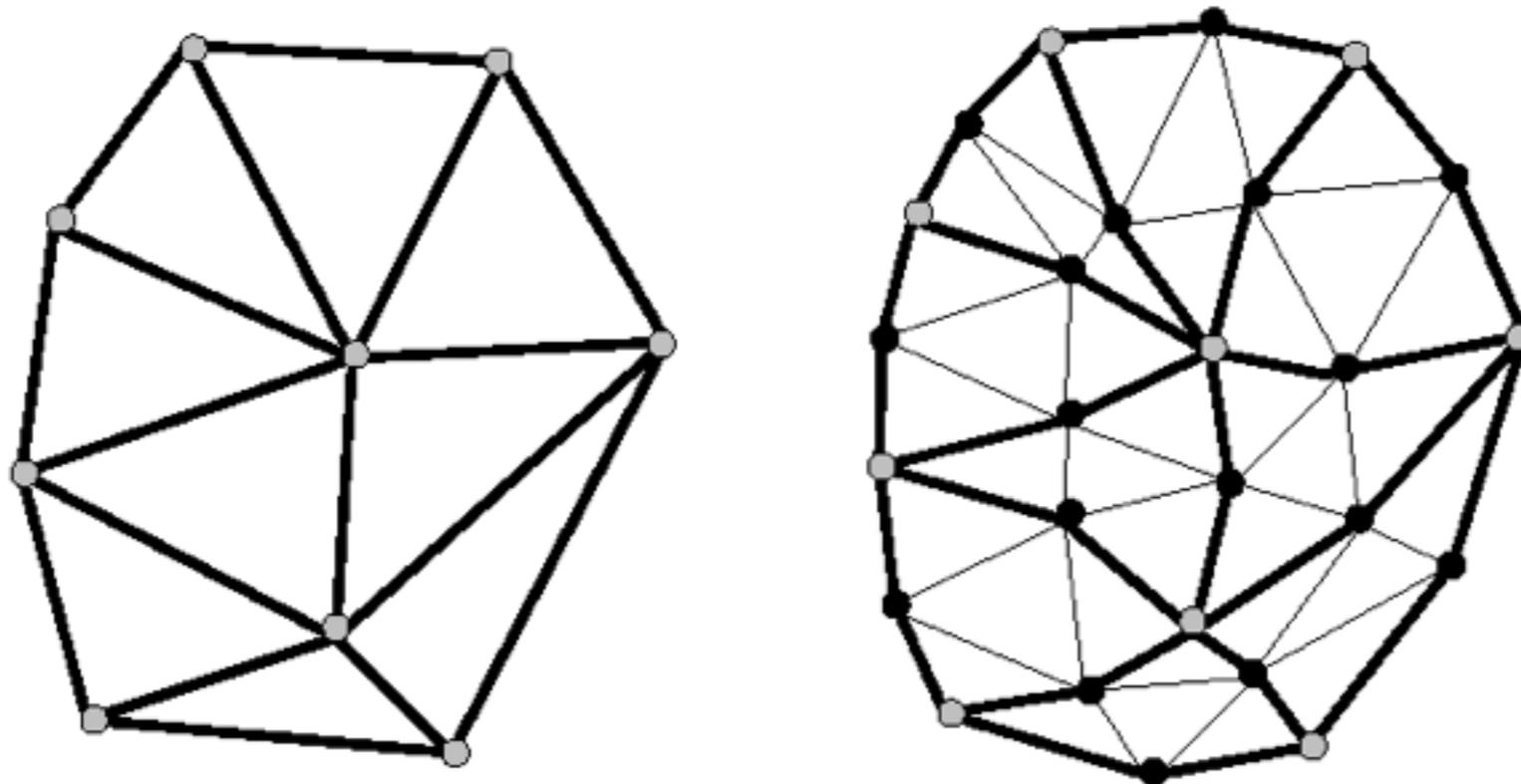
(c)



(d)

Key Questions

- How to subdivide the mesh?
 - Aim for properties like smoothness
- How to store the mesh?
 - Aim for efficiency of implementing subdivision rules



General Subdivision Scheme

- How to subdivide the mesh?

Two parts:

» Refinement:

– Add new vertices and connect (topological)

» Smoothing:

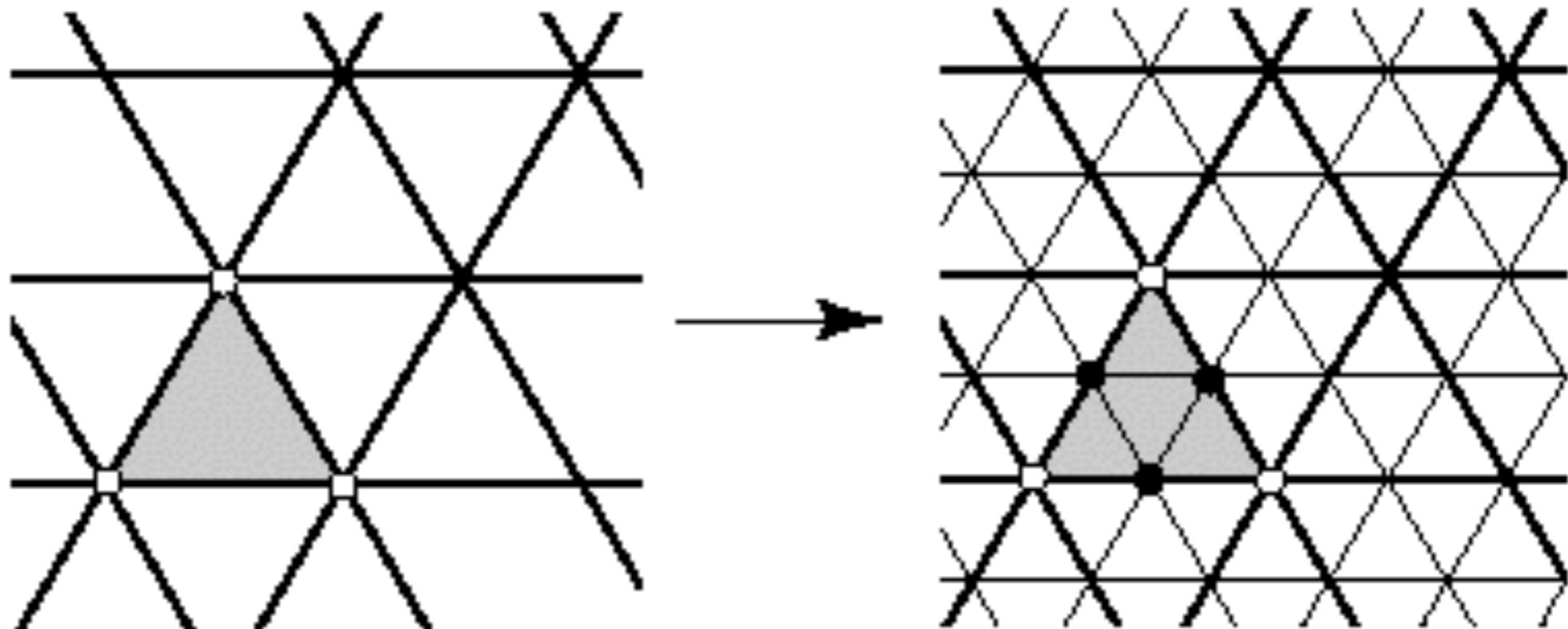
– Move vertex positions (geometric)

Loop Subdivision Scheme

- How to subdivide the mesh?

Refinement:

»Subdivide each triangle into 4 triangles by splitting each edge and connecting new vertices



Loop Subdivision Scheme

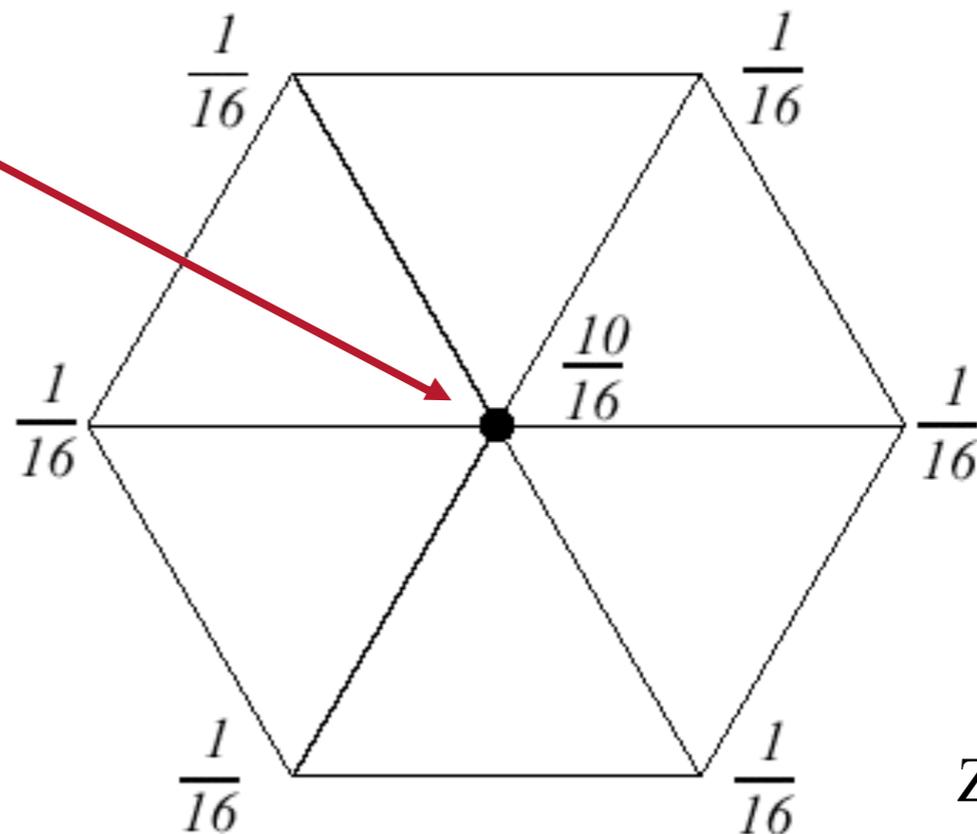
- How to subdivide the mesh:

Refinement

Smoothing:

- » Existing Vertices: Choose *new* location as weighted average of *original* vertex and its neighbors

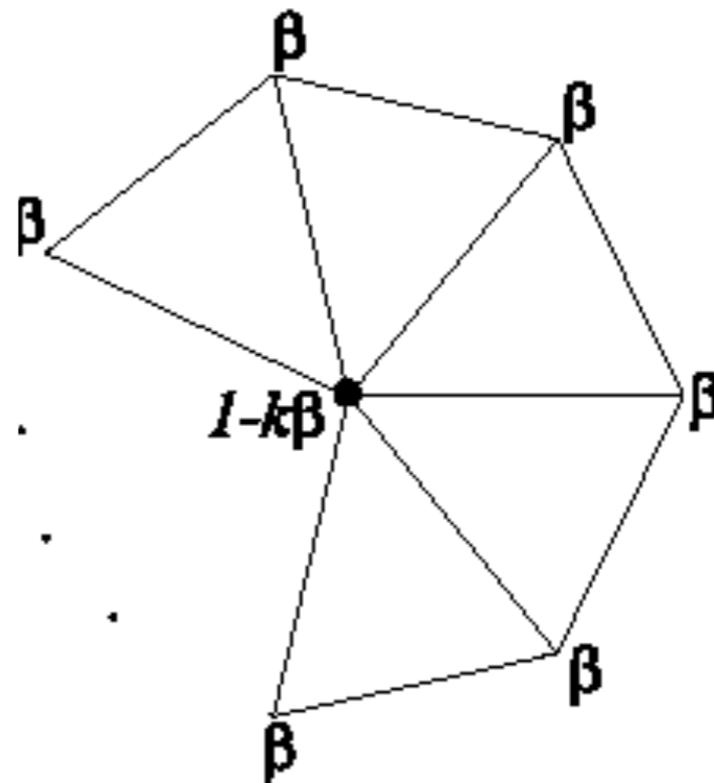
Existing vertex being moved from one level to the next



Loop Subdivision Scheme

- General rule for moving existing *interior vertices*:

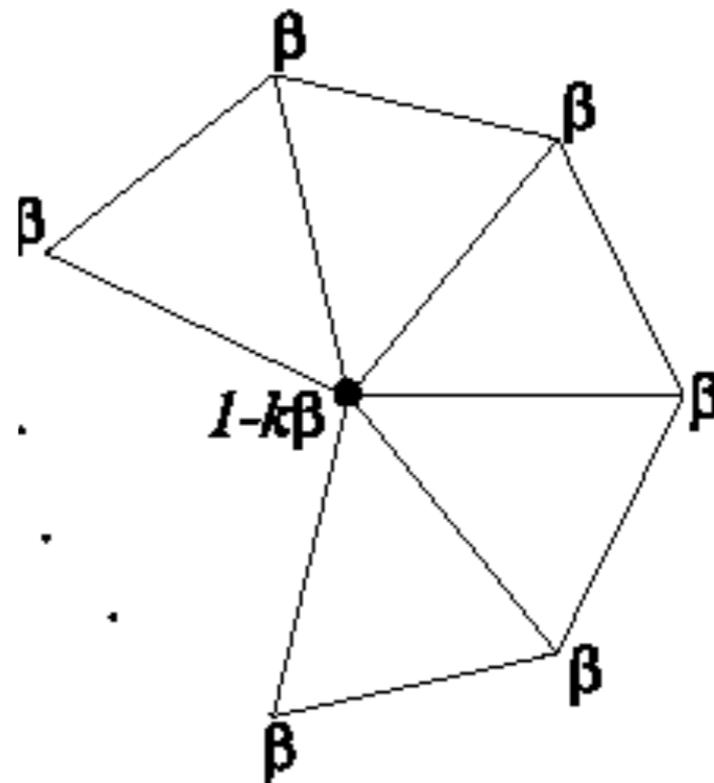
What about vertices that have more or less than 6 neighboring faces?



$$\text{new_position} = (1-k\beta)\text{original_position} + \text{sum}(\beta * \text{each_original_vertex})$$

Loop Subdivision Scheme

- General rule for moving existing *interior vertices*:



What about vertices that have more or less than 6 neighboring faces?

$0 \leq \beta \leq 1/k$:

new_

- As β increases, the contribution from adjacent vertices plays a more important role.

Where do existing vertices move?

- How to choose β ?
 - Analyze properties of limit surface
 - Interested in continuity of surface and smoothness
 - Involves calculating eigenvalues of matrices

»Original Loop

$$\beta = \frac{1}{k} \left(\frac{5}{8} - \left(\frac{3}{8} + \frac{1}{4} \cos \frac{2\pi}{k} \right)^2 \right)$$

»Warren

$$\beta = \begin{cases} \frac{3}{8k} & n > 3 \\ \frac{3}{16} & n = 3 \end{cases}$$

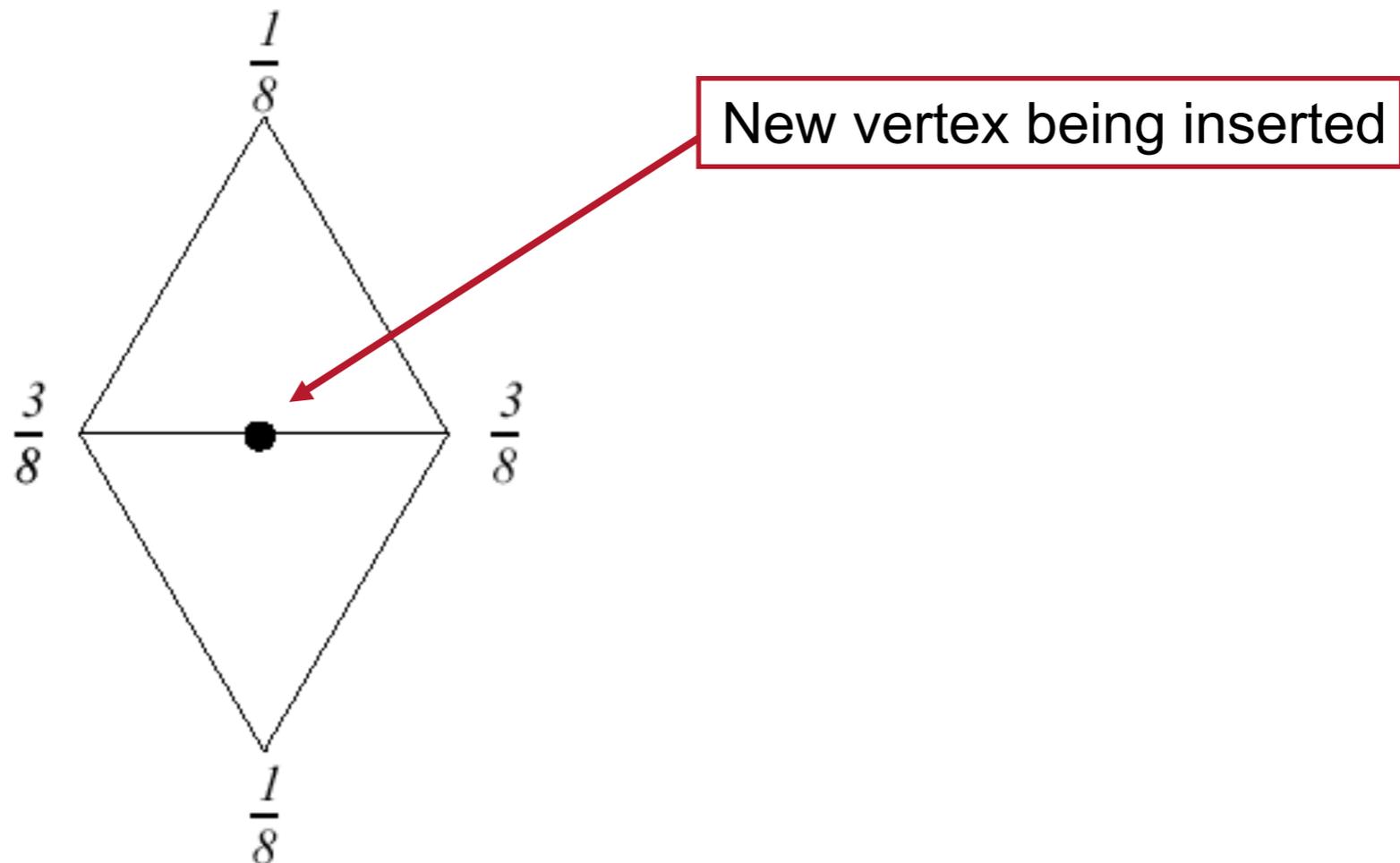
Loop Subdivision Scheme

- How to subdivide the mesh:

Refinement

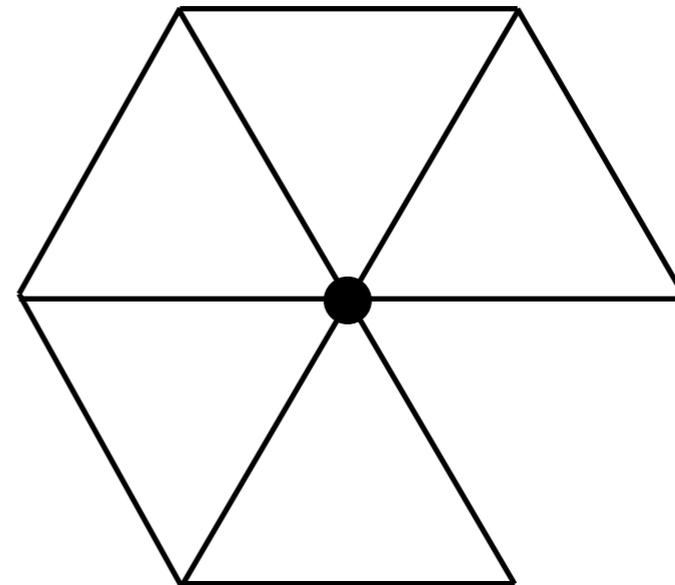
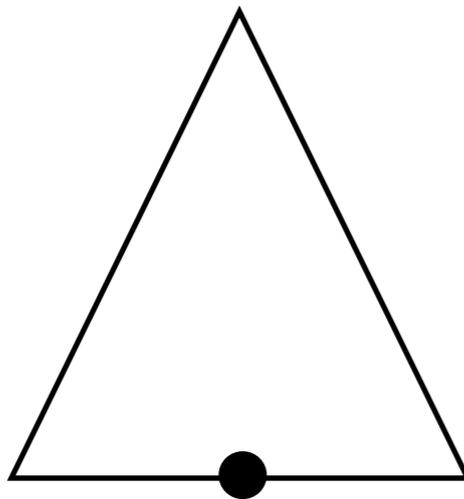
Smoothing:

» Inserted Vertices: Choose location as weighted average of *original* vertices in local neighborhood



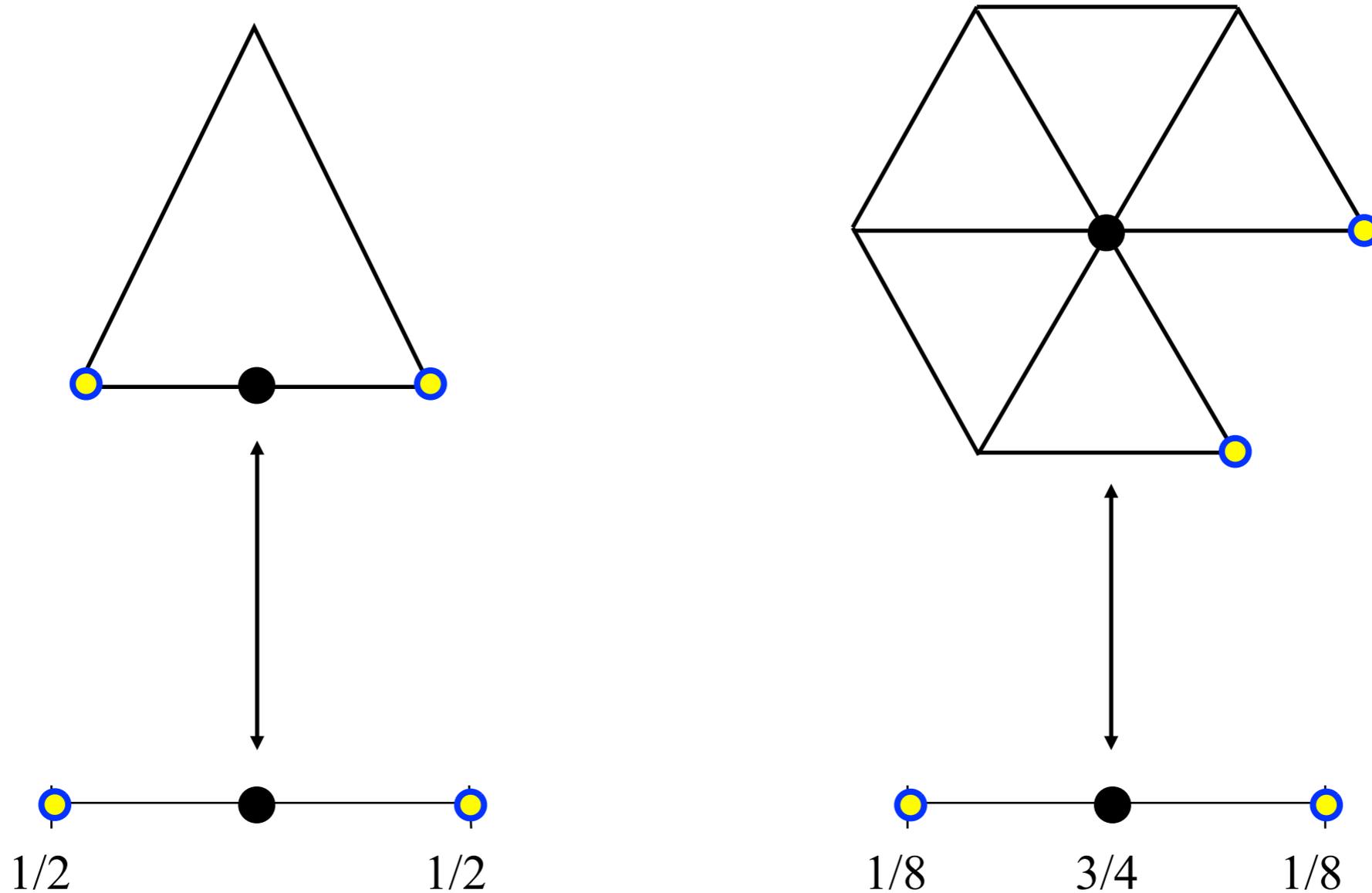
Boundary Cases?

- What about *extraordinary vertices* and *boundary edges*?
 - Existing vertex adjacent to a missing triangle
 - New vertex bordered by only one triangle

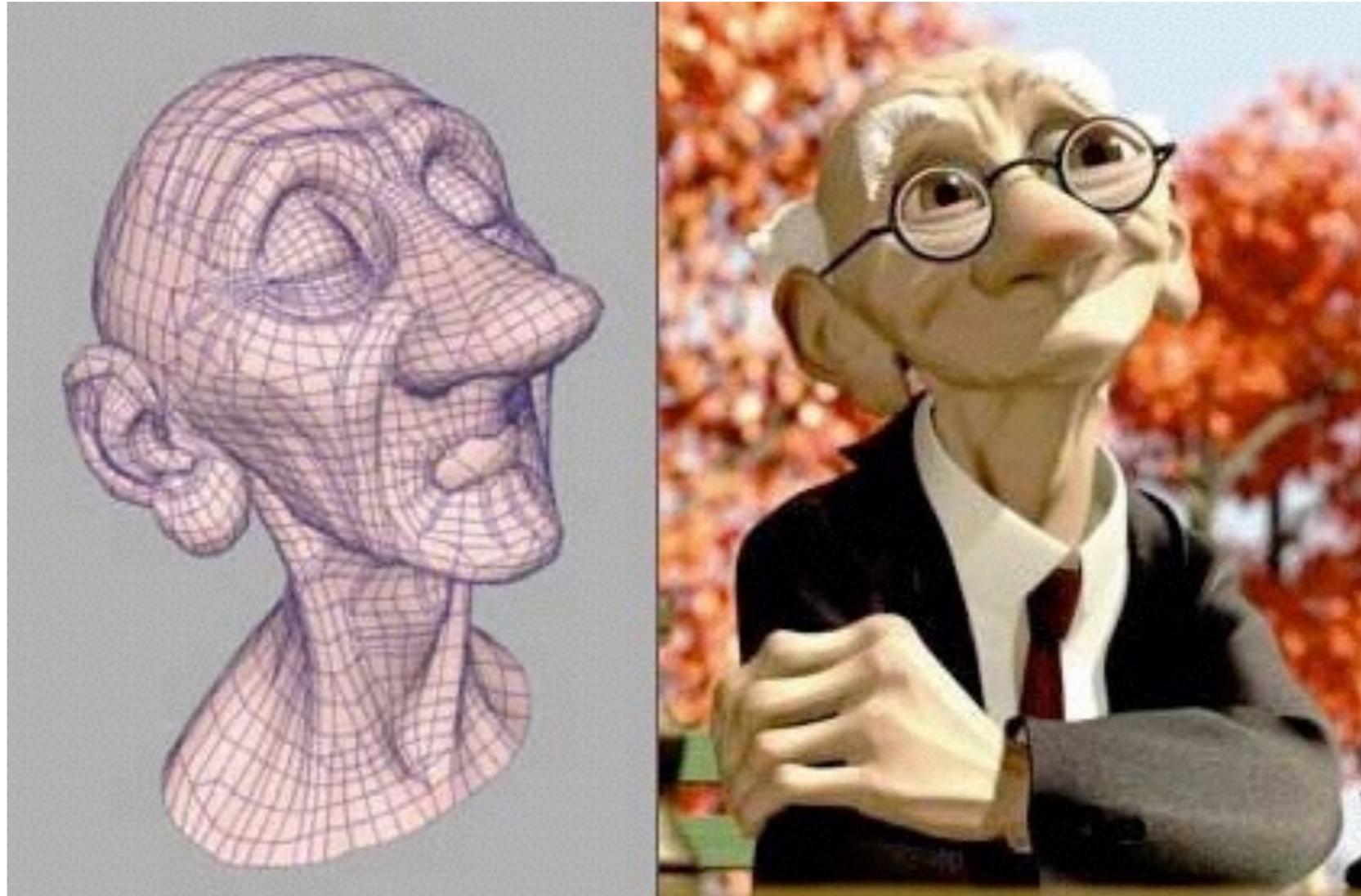


Boundary Cases?

- Rules for *extraordinary vertices* and *boundaries*:

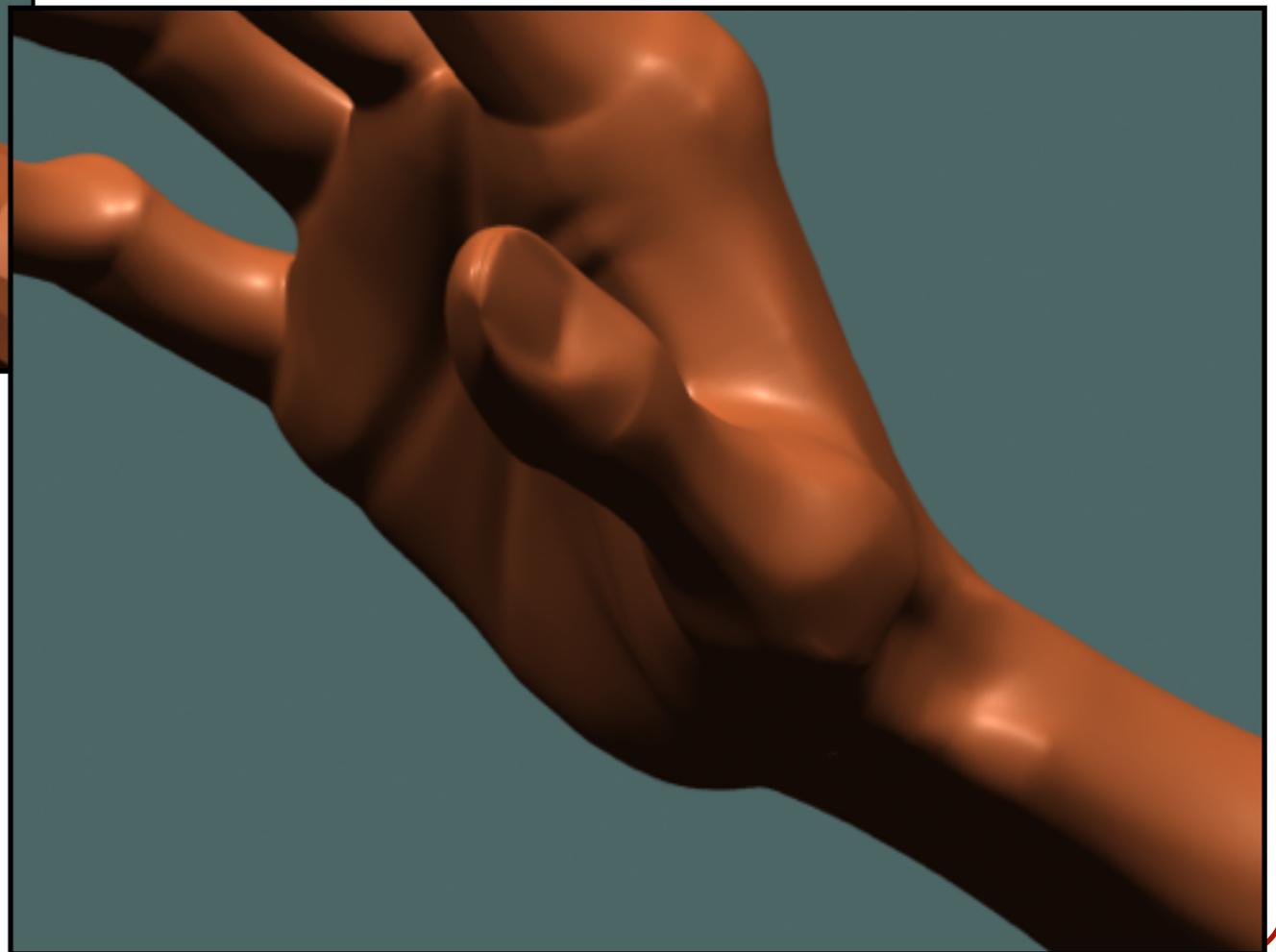


Loop Subdivision Scheme



Pixar

Loop Subdivision Scheme

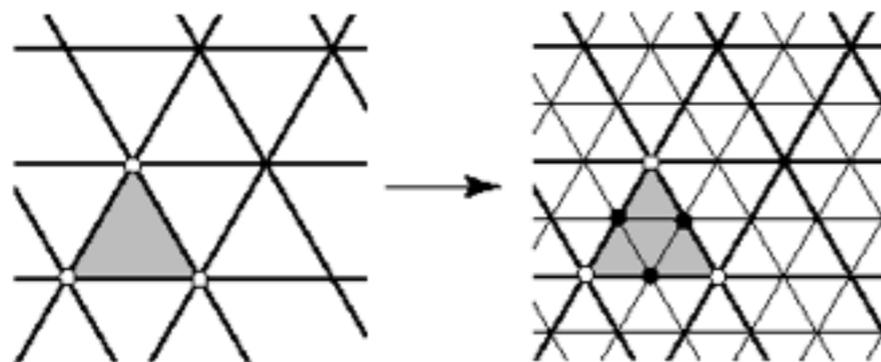


Loop Subdivision Scheme

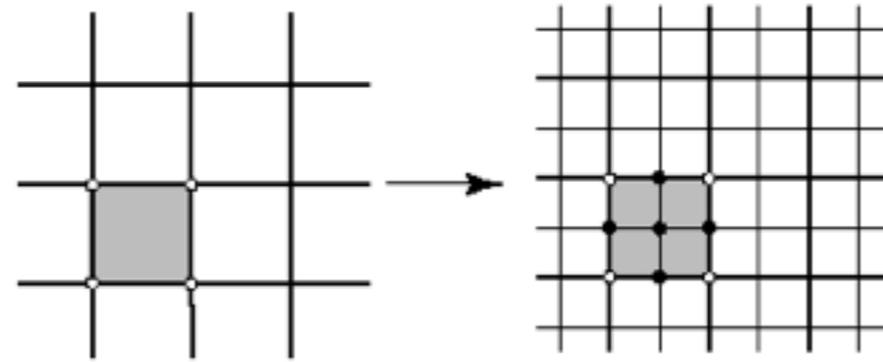
Geri's Game, *Pixar*

Subdivision Schemes

- There are different subdivision schemes
 - Different methods for refining topology
 - Different rules for positioning vertices
 - » Interpolating versus approximating



Face split for triangles

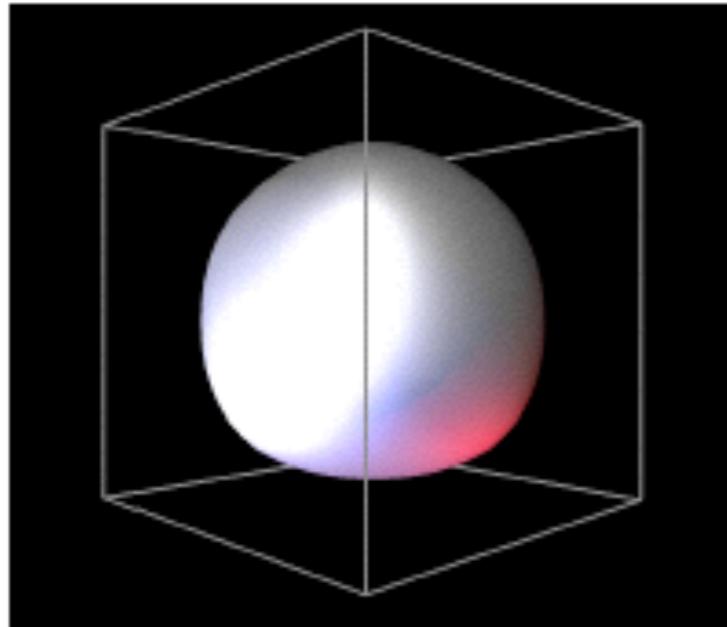


Face split for quads

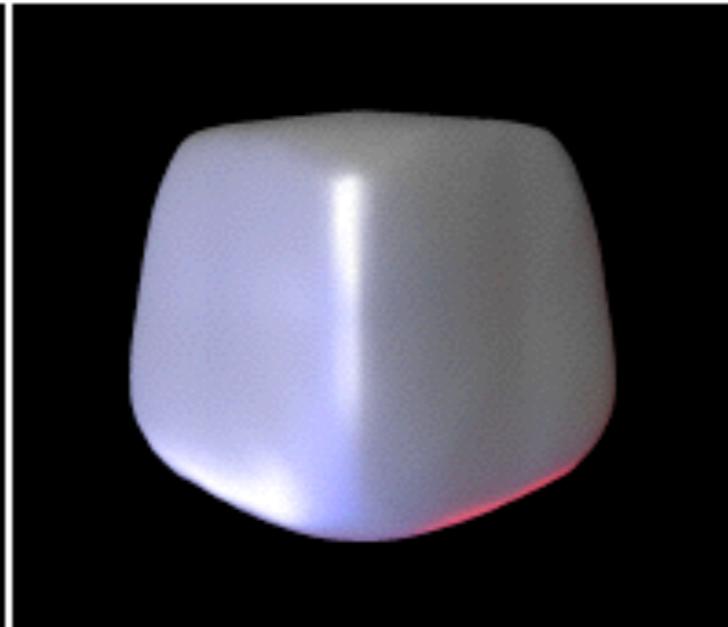
Face split		
	<i>Triangular meshes</i>	<i>Quad. meshes</i>
<i>Approximating</i>	Loop (C^2)	Catmull-Clark (C^2)
<i>Interpolating</i>	Mod. Butterfly (C^1)	Kobbelt (C^1)

Vertex split
Doo-Sabin, Midedge (C^1)
Biquartic (C^2)

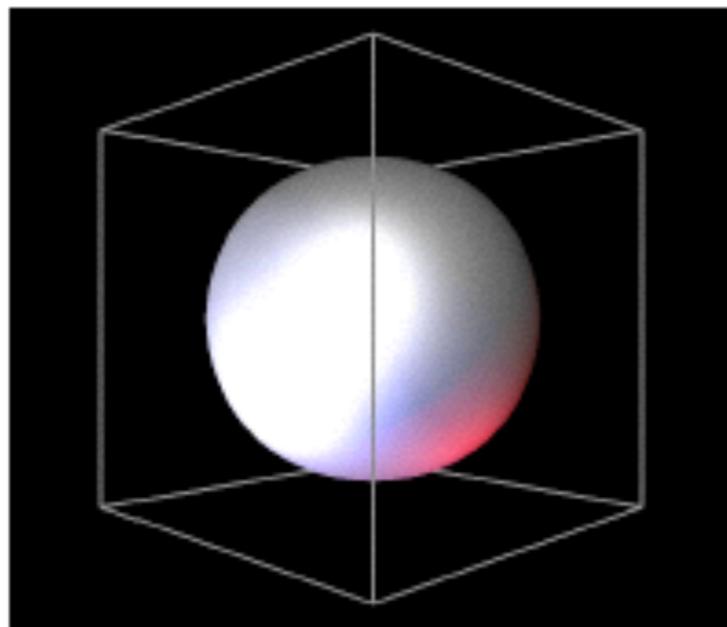
Subdivision Schemes



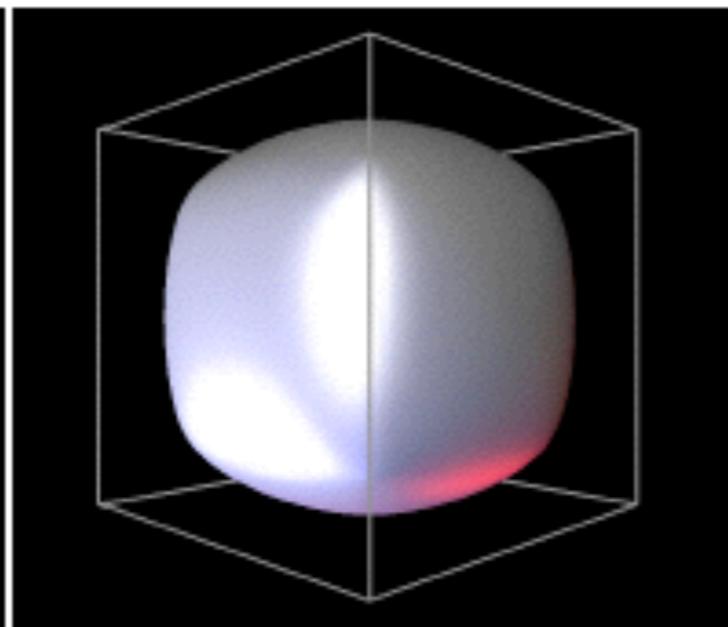
Loop



Butterfly



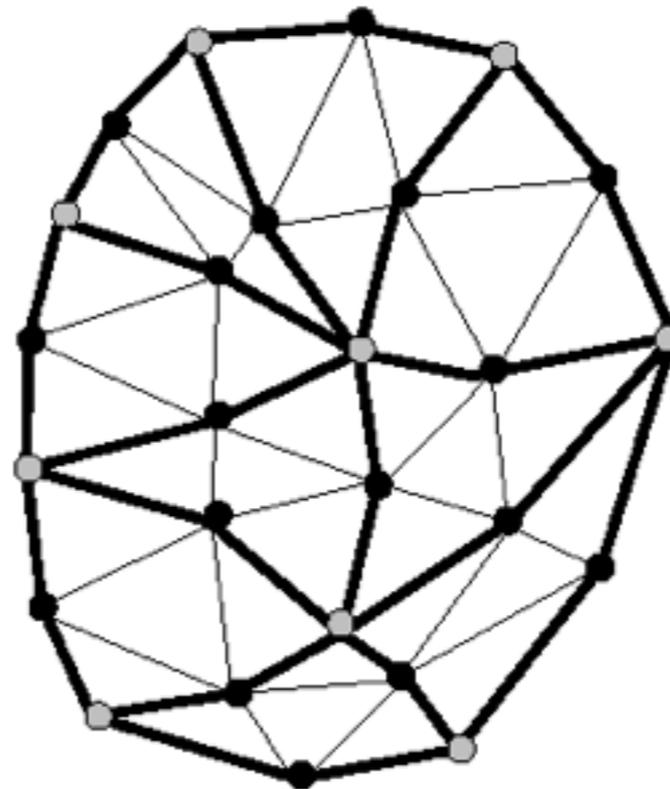
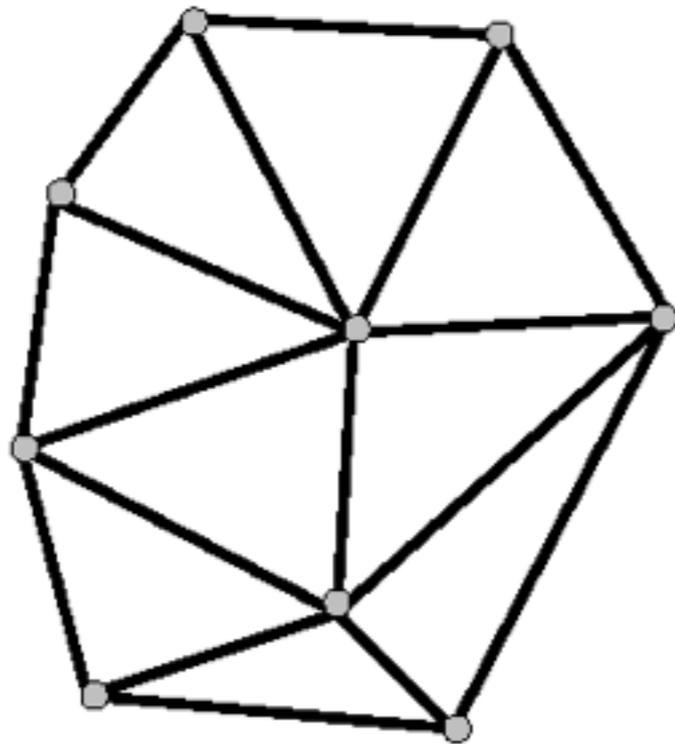
Catmull-Clark



Doo-Sabin

Key Questions

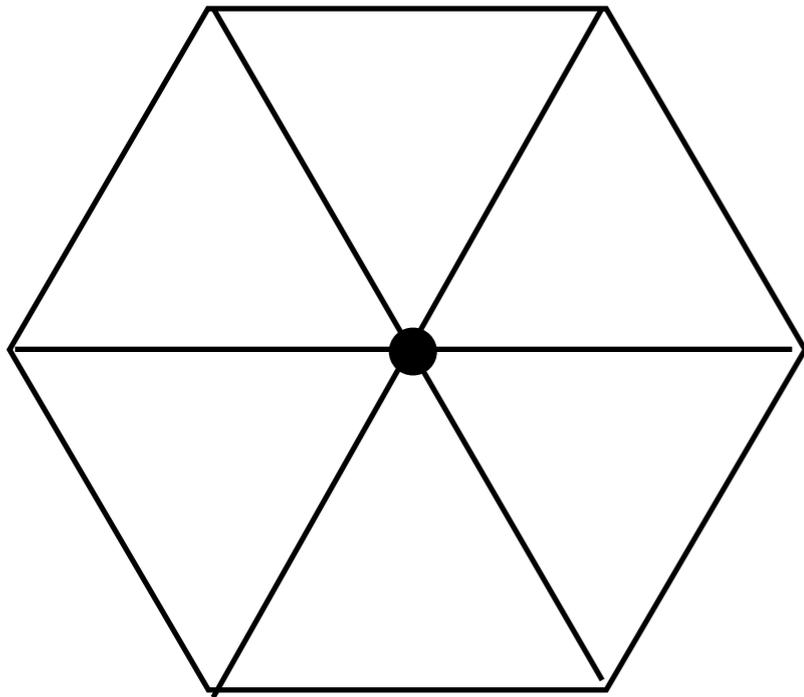
- How to refine the mesh?
 - Aim for properties like smoothness
- How to store the mesh?
 - Aim for efficiency for implementing subdivision rules



Subdivision Smoothness

To determine the smoothness of the subdivision:

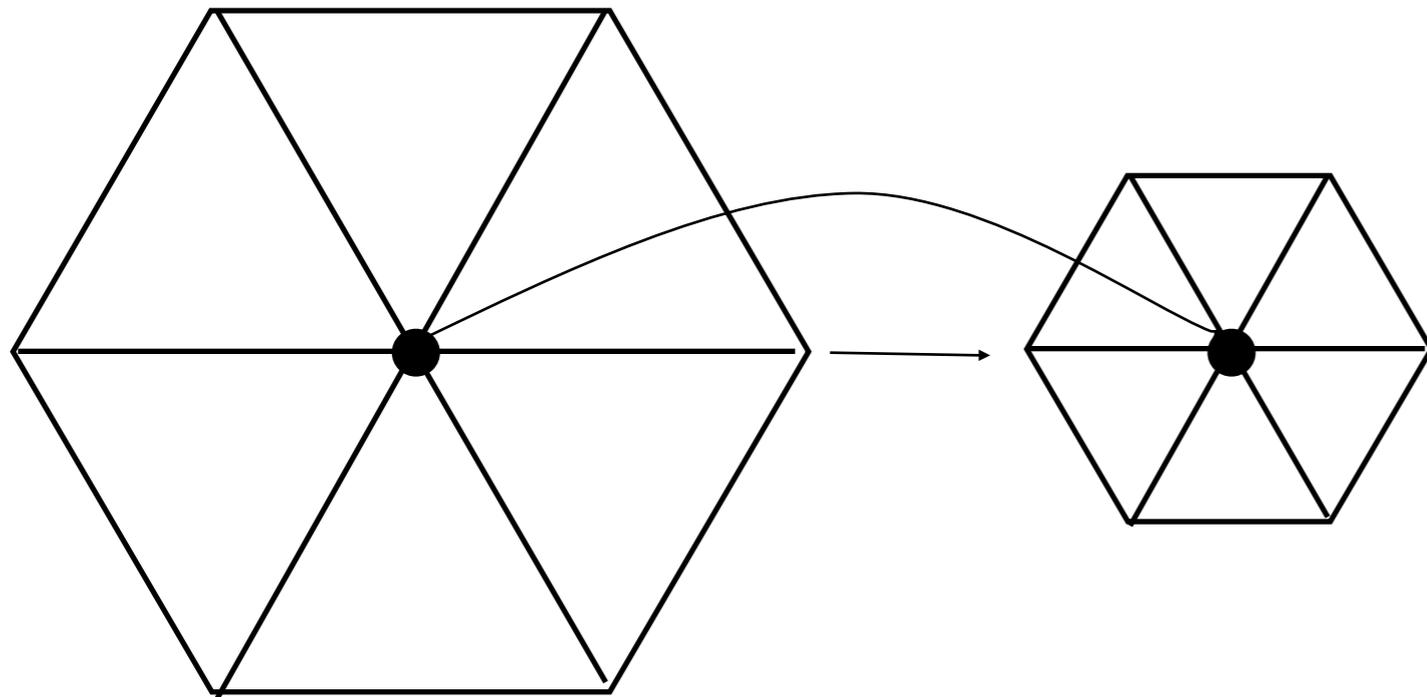
- Repeatedly apply the subdivision scheme
- Look at the neighborhood in the limit.



Subdivision Smoothness

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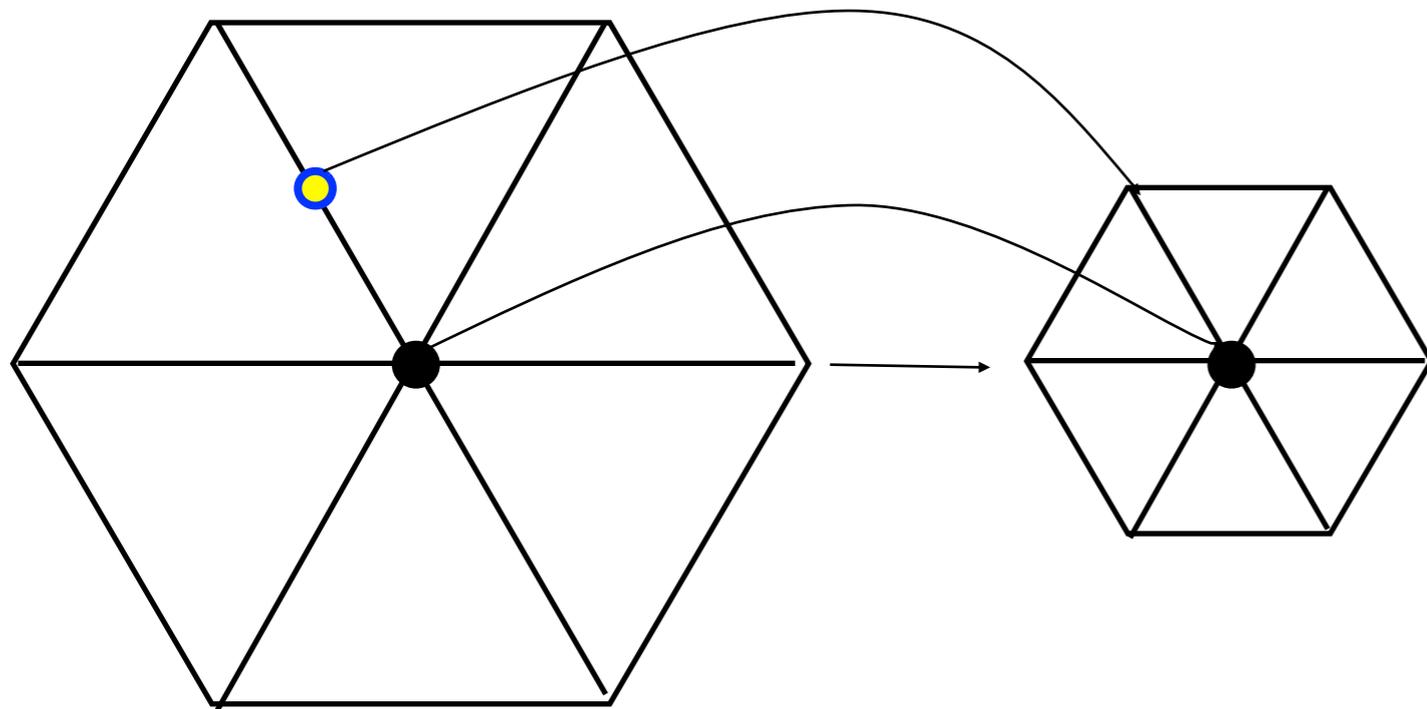
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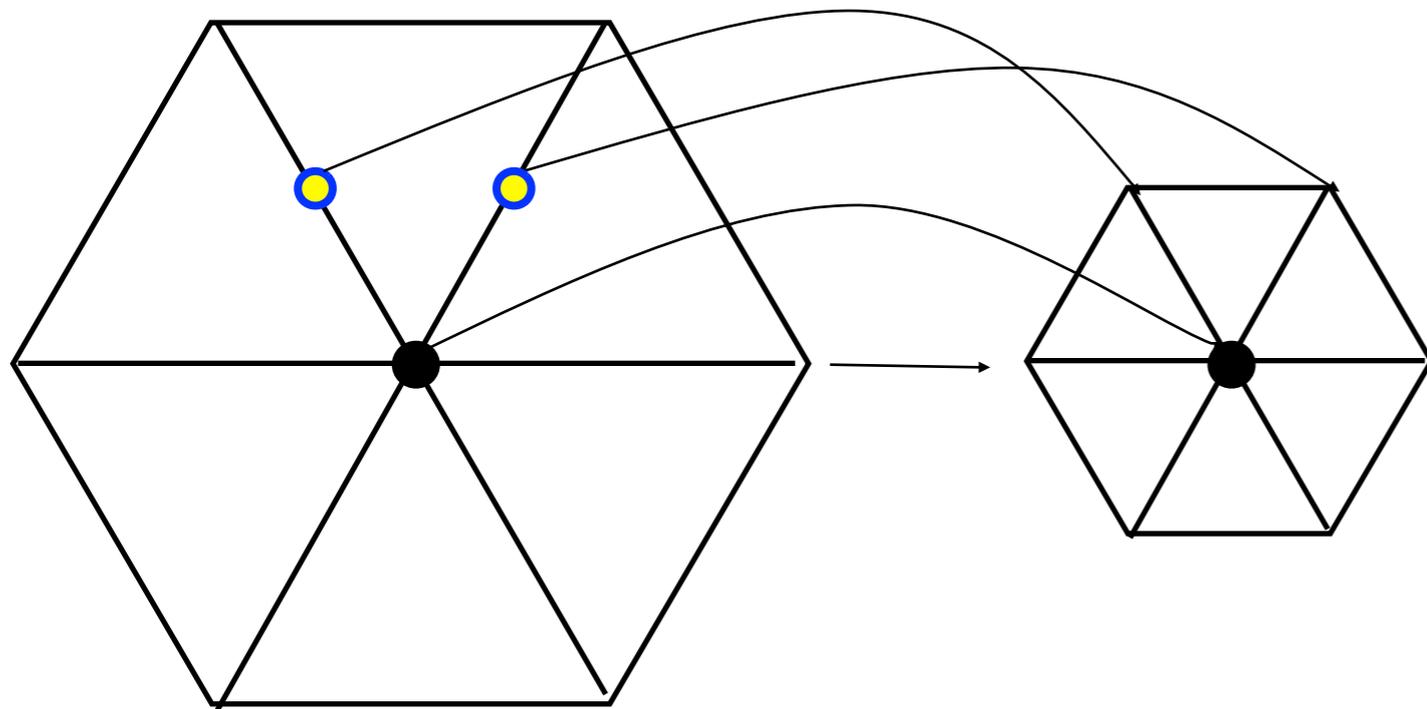
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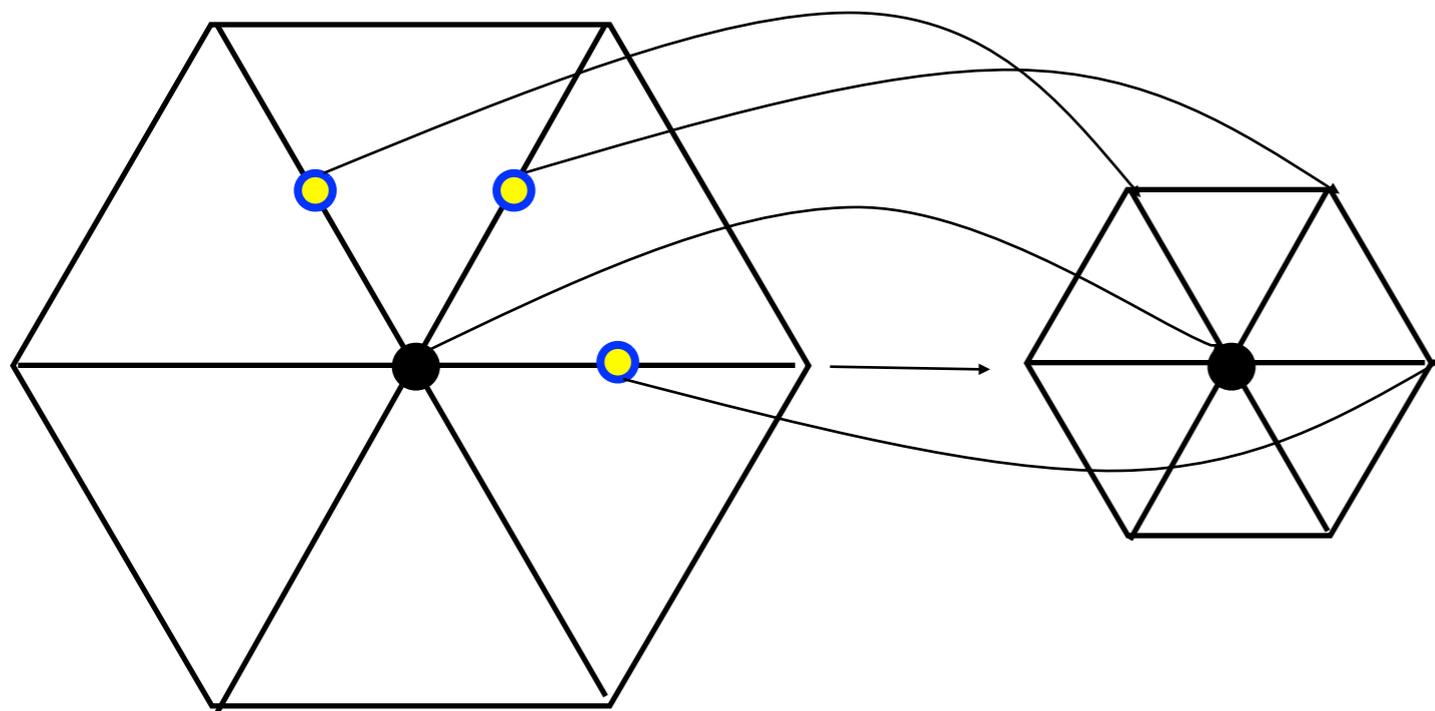
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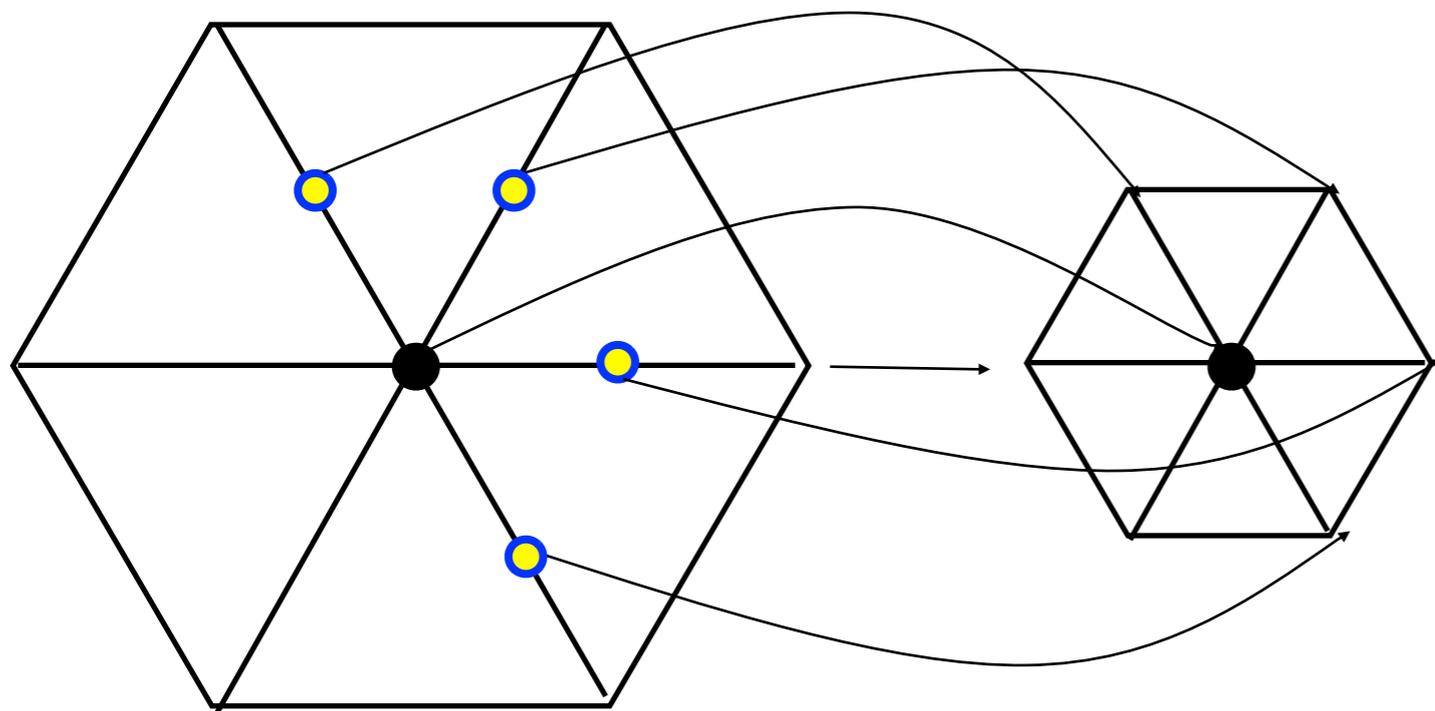
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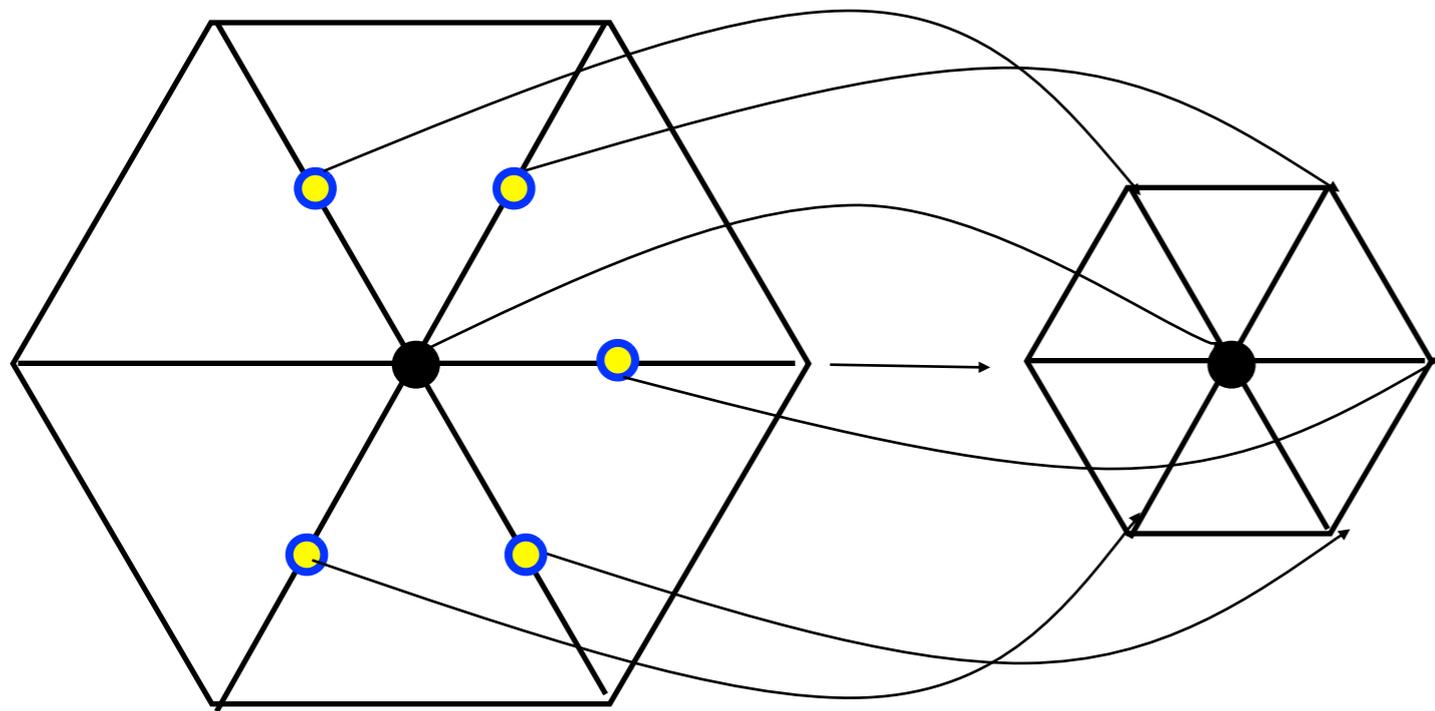
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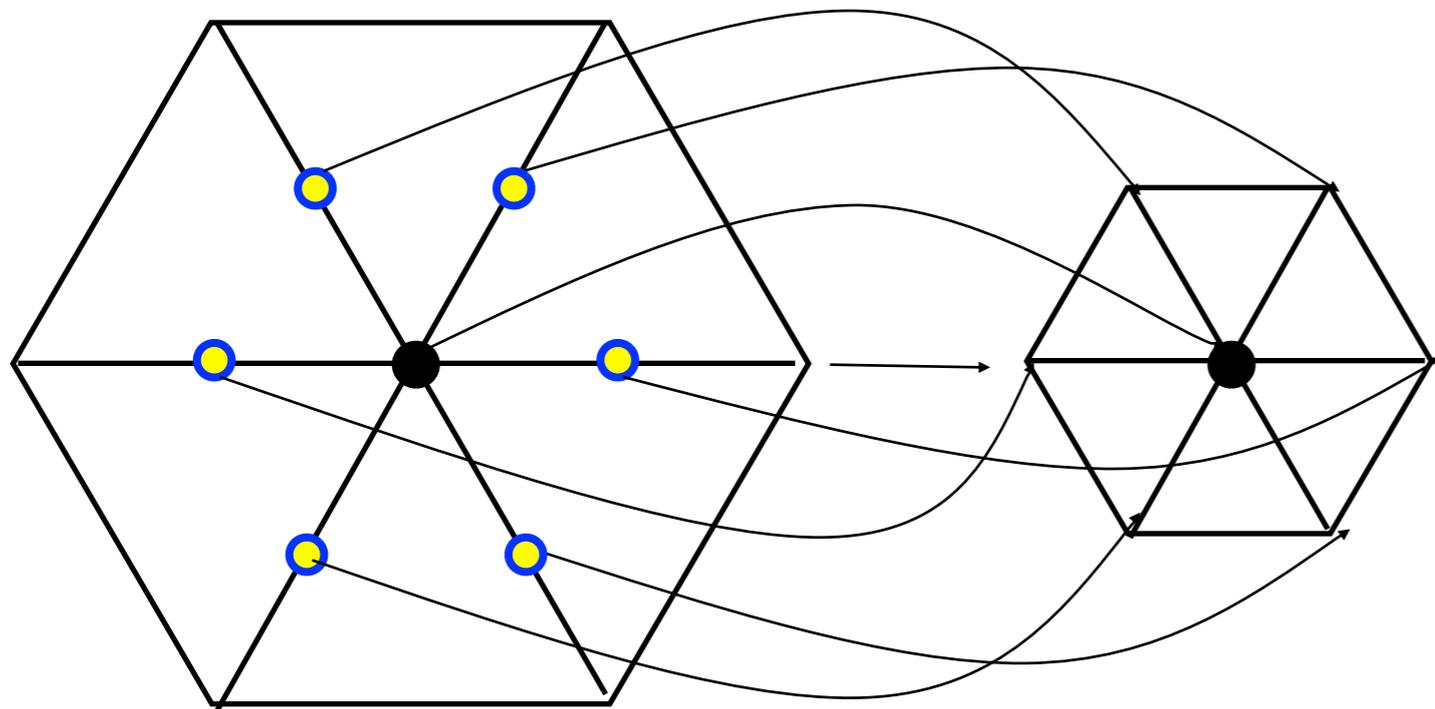
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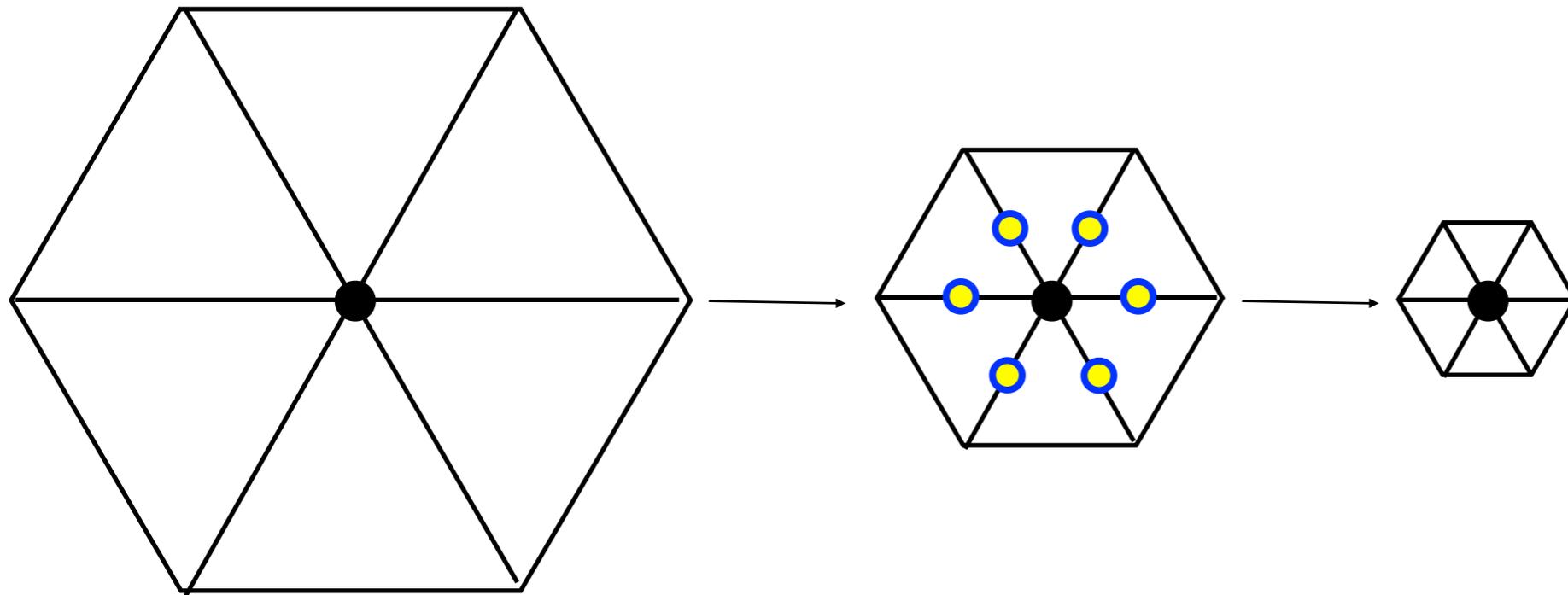
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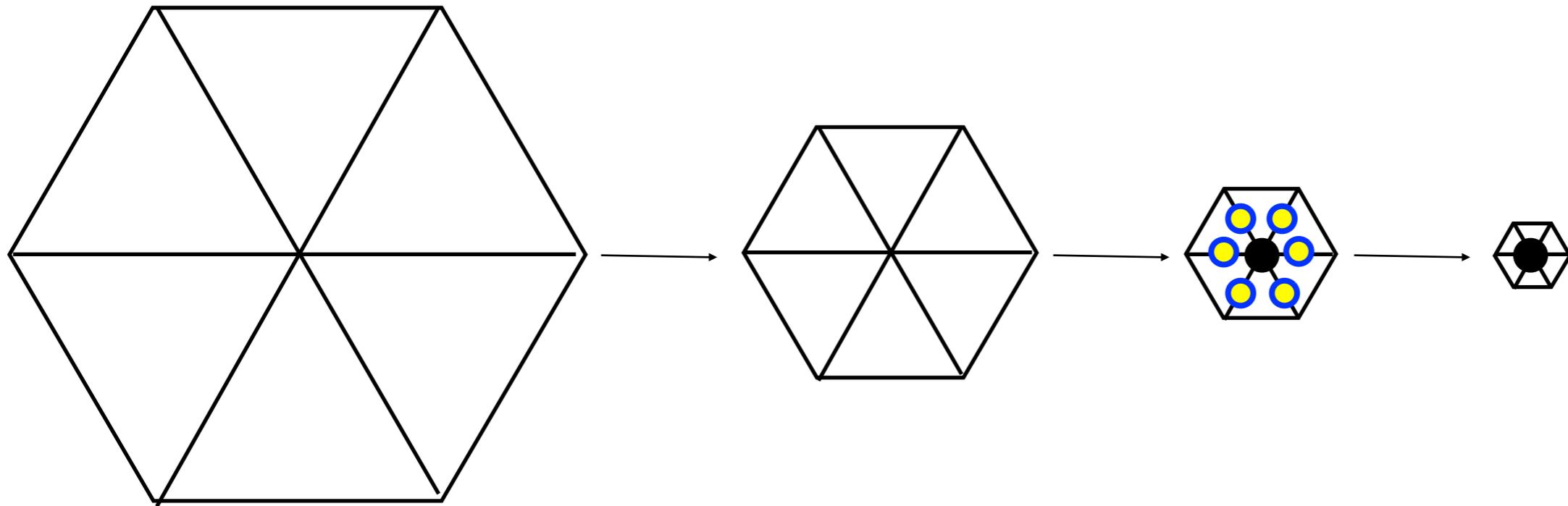
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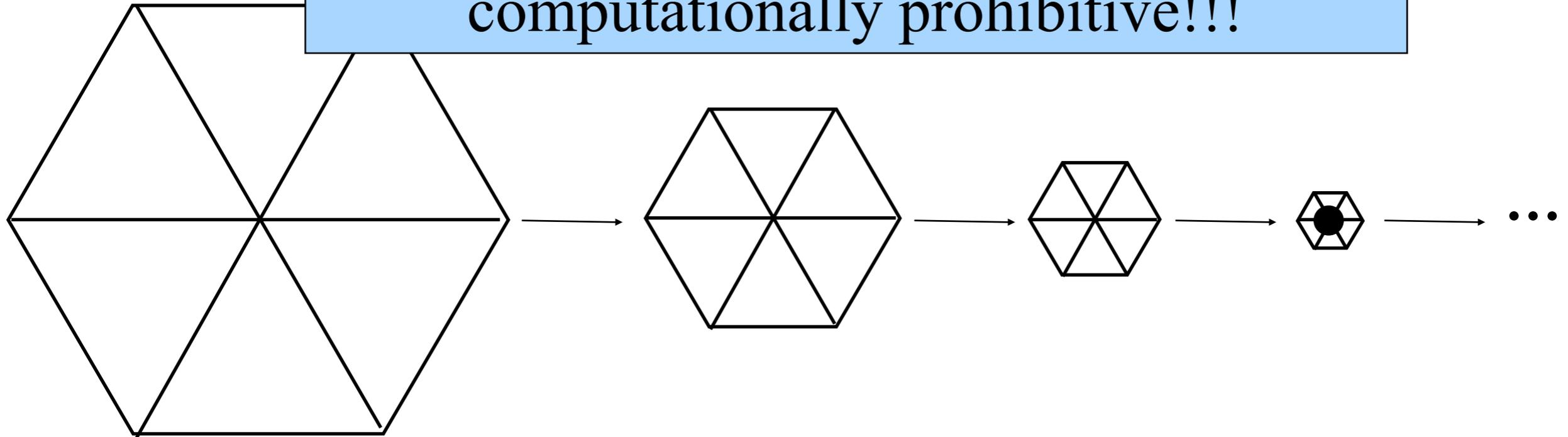


Subdivision Smoothness

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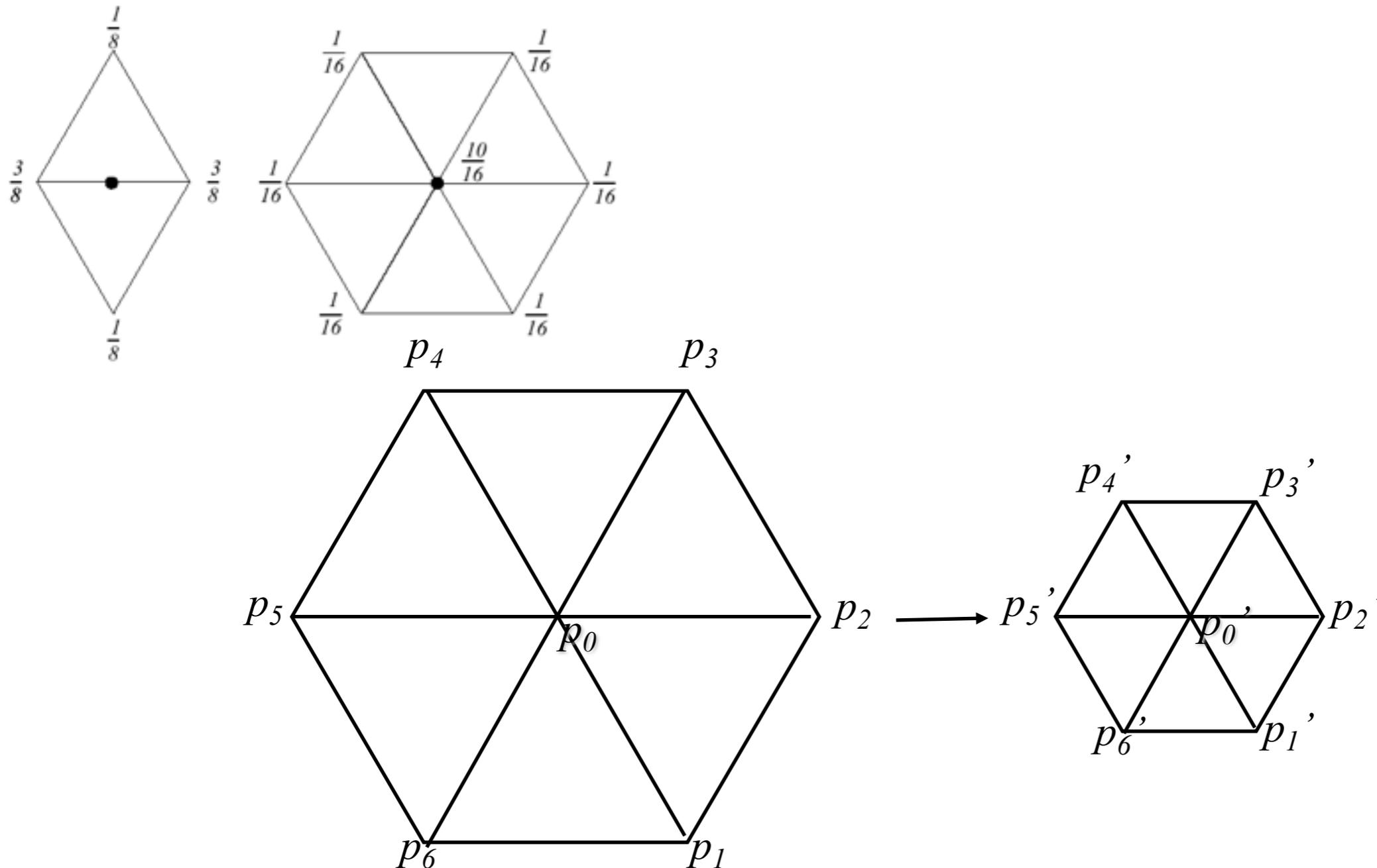
- Repeatedly apply the subdivision scheme
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Computing infinitely many iterations is computationally prohibitive!!!



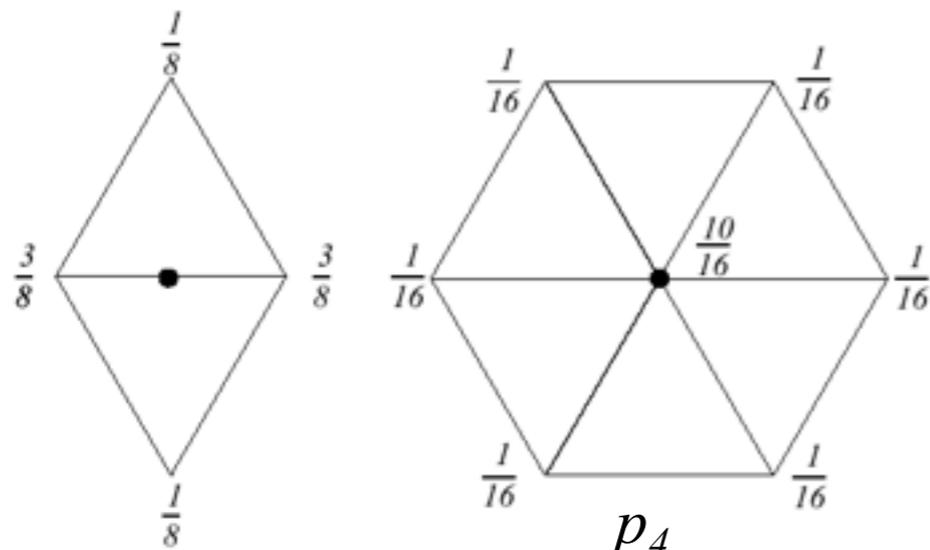
Subdivision Matrix

- Compute the new positions/vertices as a linear combination of previous ones.



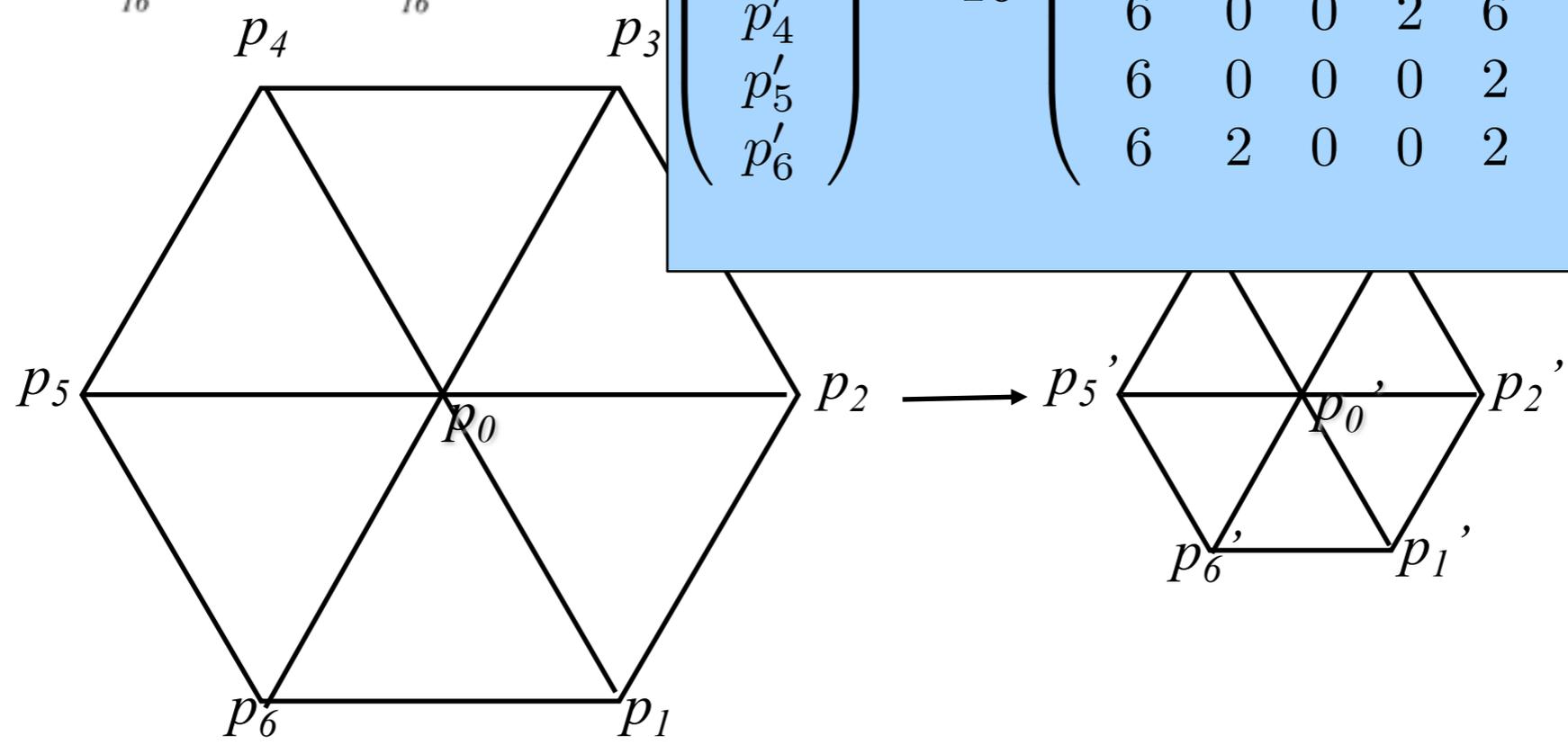
Subdivision Matrix

- Compute the new positions/vertices as a linear combination of previous ones.



Subdivision Matrix

$$\begin{pmatrix} p'_0 \\ p'_1 \\ p'_2 \\ p'_3 \\ p'_4 \\ p'_5 \\ p'_6 \end{pmatrix} = \frac{1}{16} \begin{pmatrix} 10 & 1 & 1 & 1 & 1 & 1 & 1 \\ 6 & 6 & 2 & 0 & 0 & 0 & 2 \\ 6 & 2 & 6 & 2 & 0 & 0 & 0 \\ 6 & 0 & 2 & 6 & 2 & 0 & 0 \\ 6 & 0 & 0 & 2 & 6 & 2 & 0 \\ 6 & 0 & 0 & 0 & 2 & 6 & 2 \\ 6 & 2 & 0 & 0 & 2 & 2 & 6 \end{pmatrix} \begin{pmatrix} p_0 \\ p_1 \\ p_2 \\ p_3 \\ p_4 \\ p_5 \\ p_6 \end{pmatrix}$$



Subdivision Matrix

- Compute the new positions/vertices as a linear combination of previous ones.
- To find the limit position of p_0 , repeatedly apply the subdivision matrix.

$$\begin{pmatrix} p_0^{(n)} \\ p_1^{(n)} \\ p_2^{(n)} \\ p_3^{(n)} \\ p_4^{(n)} \\ p_5^{(n)} \\ p_6^{(n)} \end{pmatrix} = \frac{1}{16} \begin{pmatrix} 10 & 1 & 1 & 1 & 1 & 1 & 1 \\ 6 & 6 & 2 & 0 & 0 & 0 & 2 \\ 6 & 2 & 6 & 2 & 0 & 0 & 0 \\ 6 & 0 & 2 & 6 & 2 & 0 & 0 \\ 6 & 0 & 0 & 2 & 6 & 2 & 0 \\ 6 & 0 & 0 & 0 & 2 & 6 & 2 \\ 6 & 2 & 0 & 0 & 2 & 2 & 6 \end{pmatrix}^n \begin{pmatrix} p_0 \\ p_1 \\ p_2 \\ p_3 \\ p_4 \\ p_5 \\ p_6 \end{pmatrix}$$

Subdivision Matrix

- Compute the new positions/vertices as a linear combination of previous ones.
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$$\begin{pmatrix} p_0^{(n)} \\ p_1^{(n)} \end{pmatrix} = \begin{pmatrix} 10 & 1 & 1 & 1 & 1 & 1 & 1 \\ 6 & 6 & 2 & 0 & 0 & 0 & 2 \end{pmatrix}^n \begin{pmatrix} p_0 \\ p_1 \end{pmatrix}$$

If, after a change of basis we have $M=A^{-1}DA$, where D is a diagonal matrix, then:

$$M^n=A^{-1}D^nA,$$

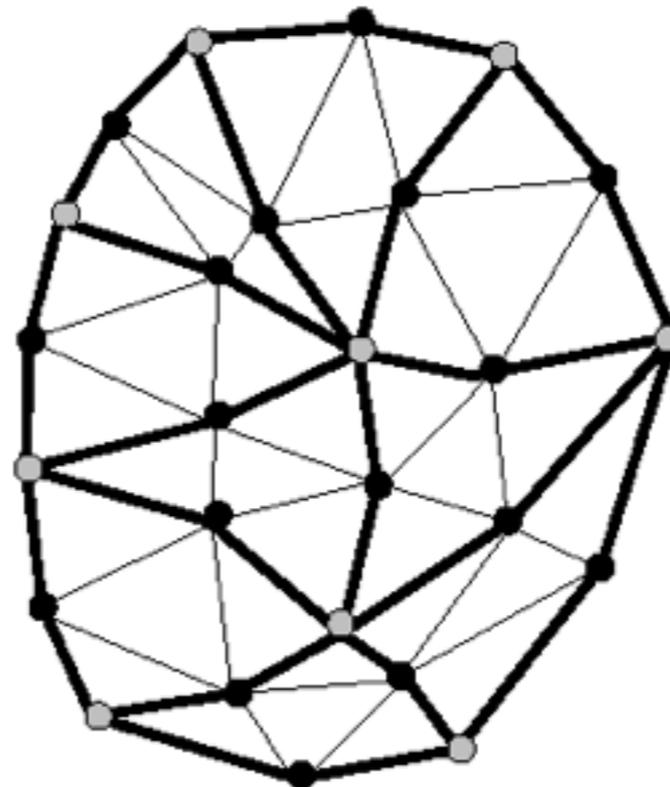
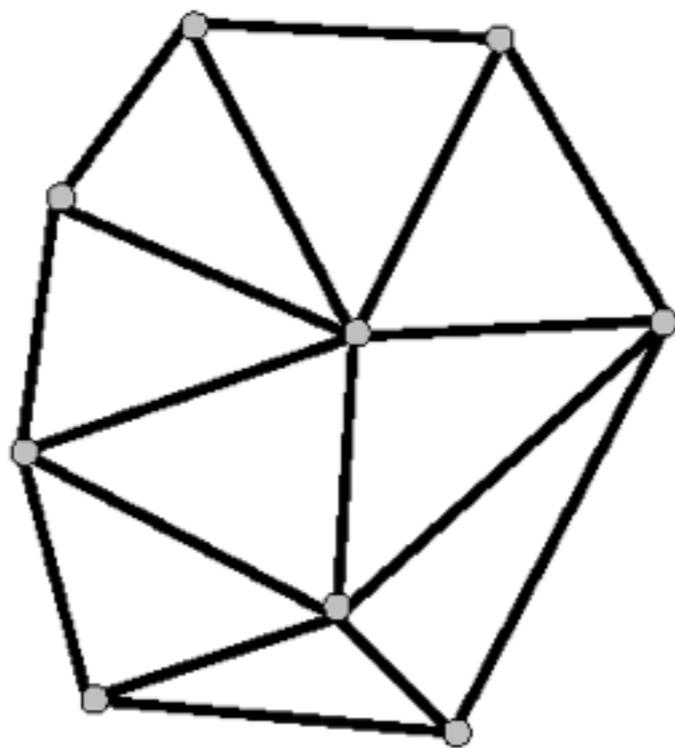
Since D is diagonal, raising D to the n -th power just amounts to raising each of the diagonal entries of D to the n -th power.

Subdivision Modeling

- ZBrush Modeling Session

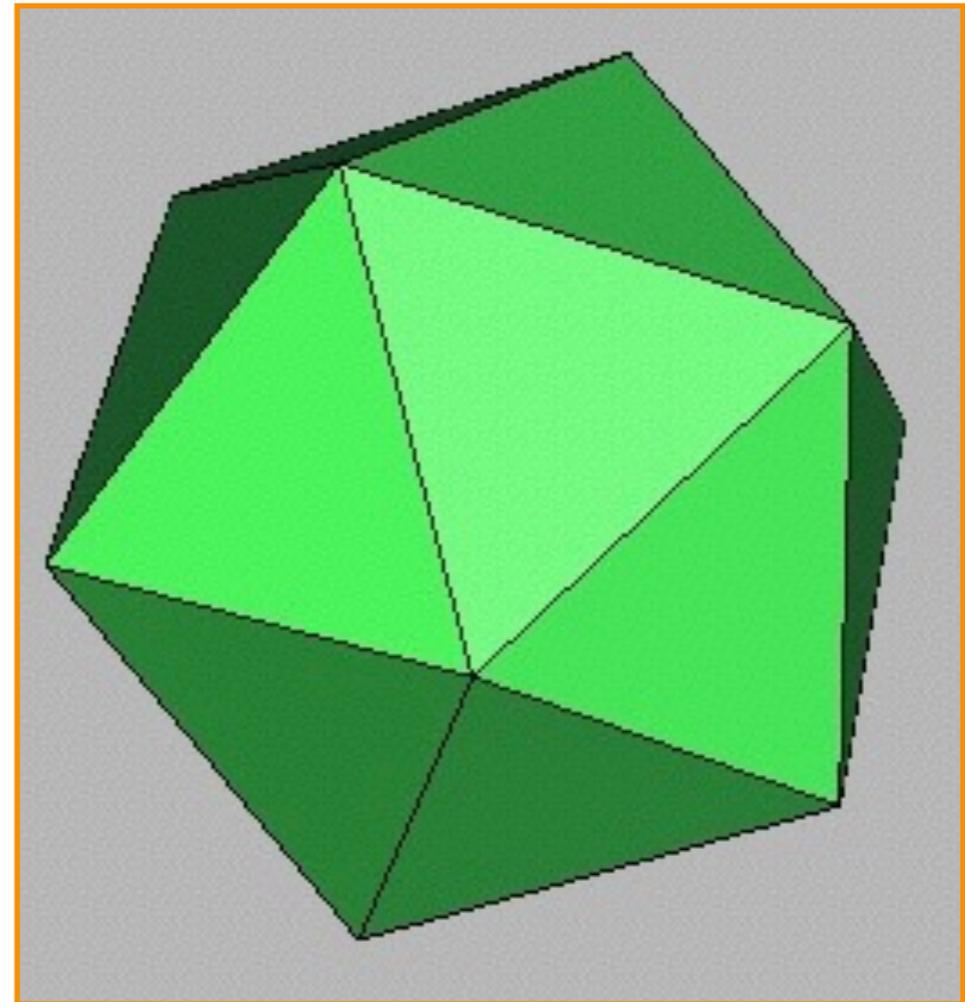
Key Questions

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 - Aim for properties like smoothness
- **How to store the mesh?**
 - Aim for efficiency for implementing subdivision rules



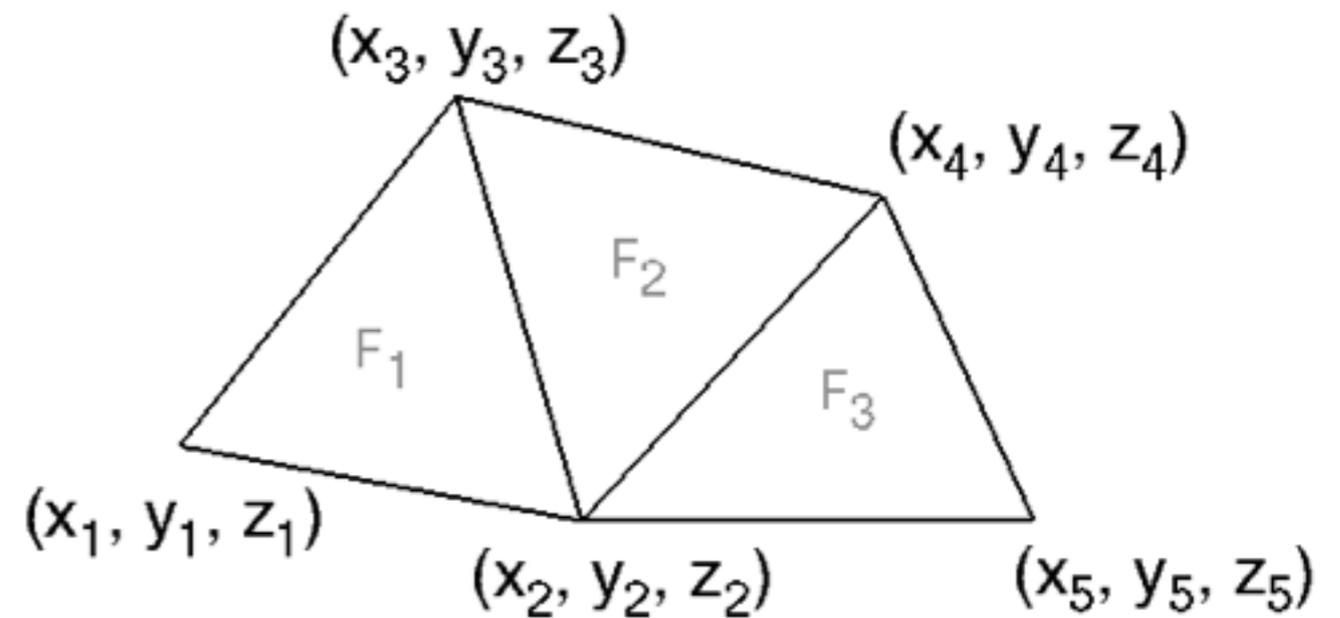
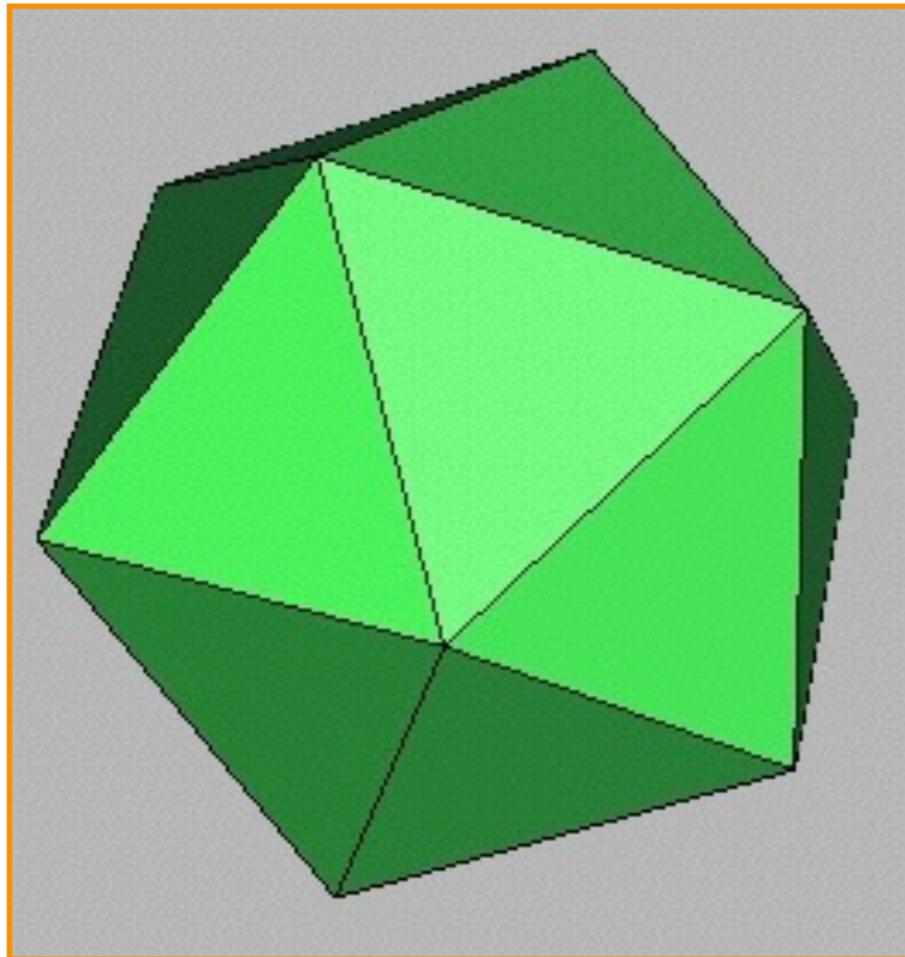
Polygon Meshes

- Mesh Representations
 - Independent faces
 - Vertex and face tables
 - Adjacency lists
 - Winged-Edge



Independent Faces

- Each face lists vertex coordinates

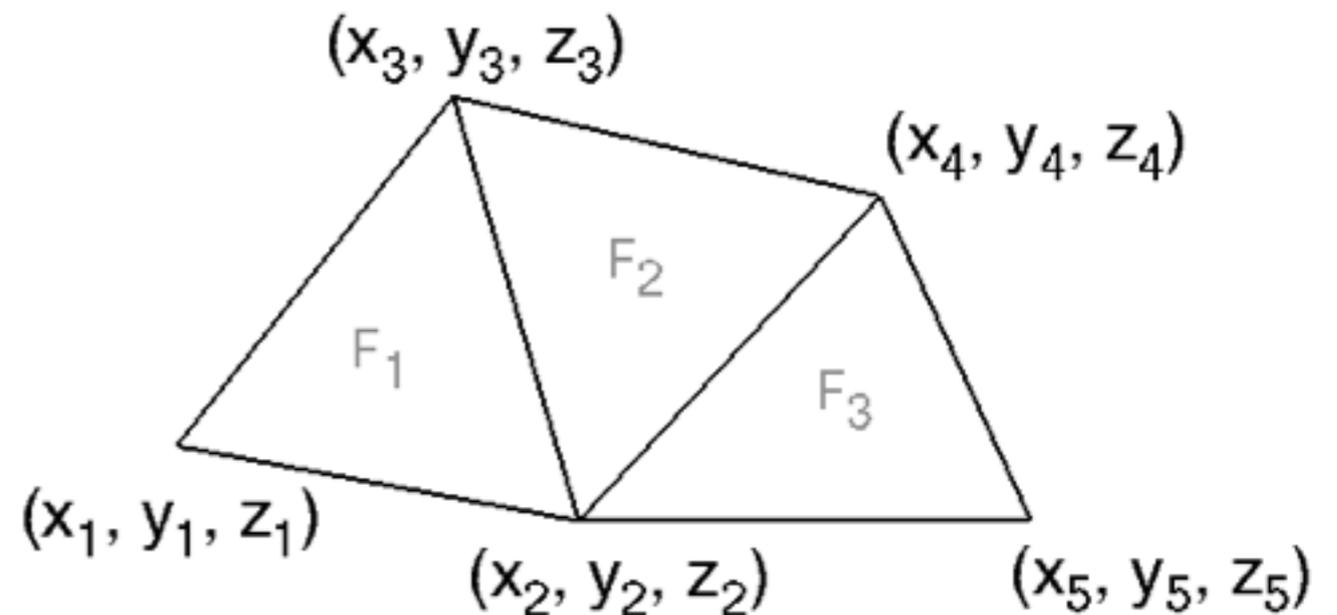
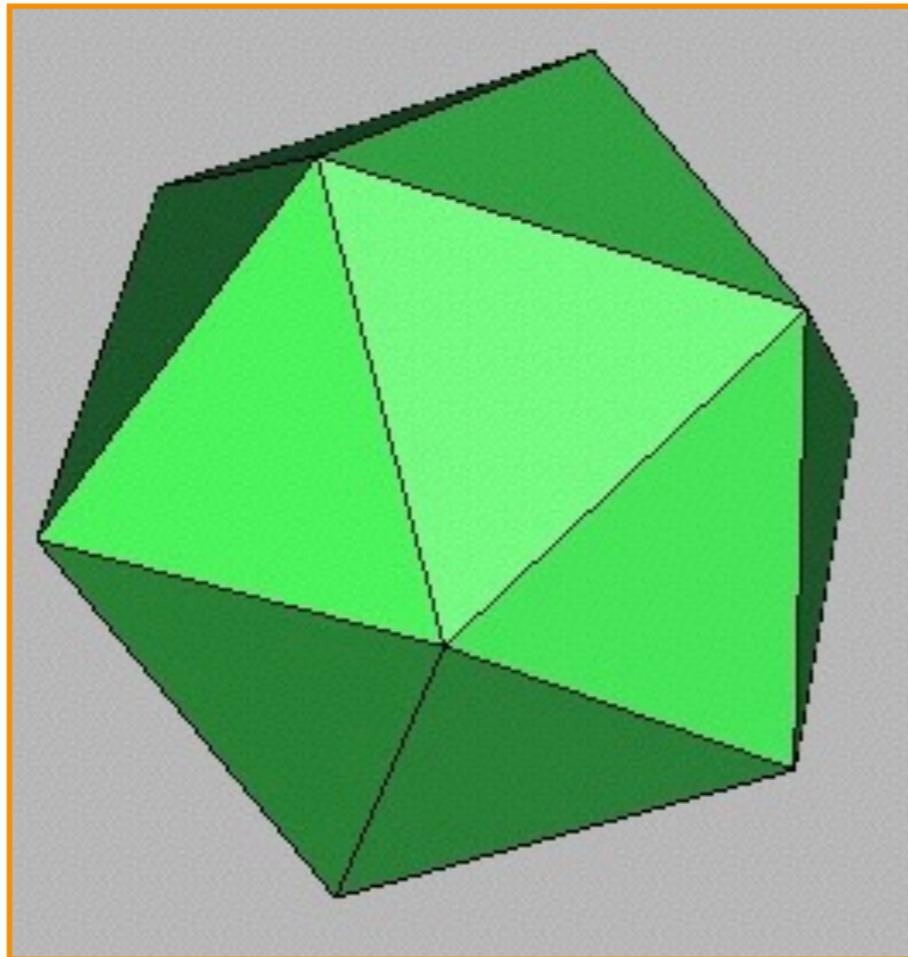


FACE TABLE

F_1	(x_1, y_1, z_1)	(x_2, y_2, z_2)	(x_3, y_3, z_3)
F_2	(x_2, y_2, z_2)	(x_4, y_4, z_4)	(x_3, y_3, z_3)
F_3	(x_2, y_2, z_2)	(x_5, y_5, z_5)	(x_4, y_4, z_4)

Independent Faces

- Each face lists vertex coordinates
 - ✗ Redundant vertices
 - ✗ No topology information

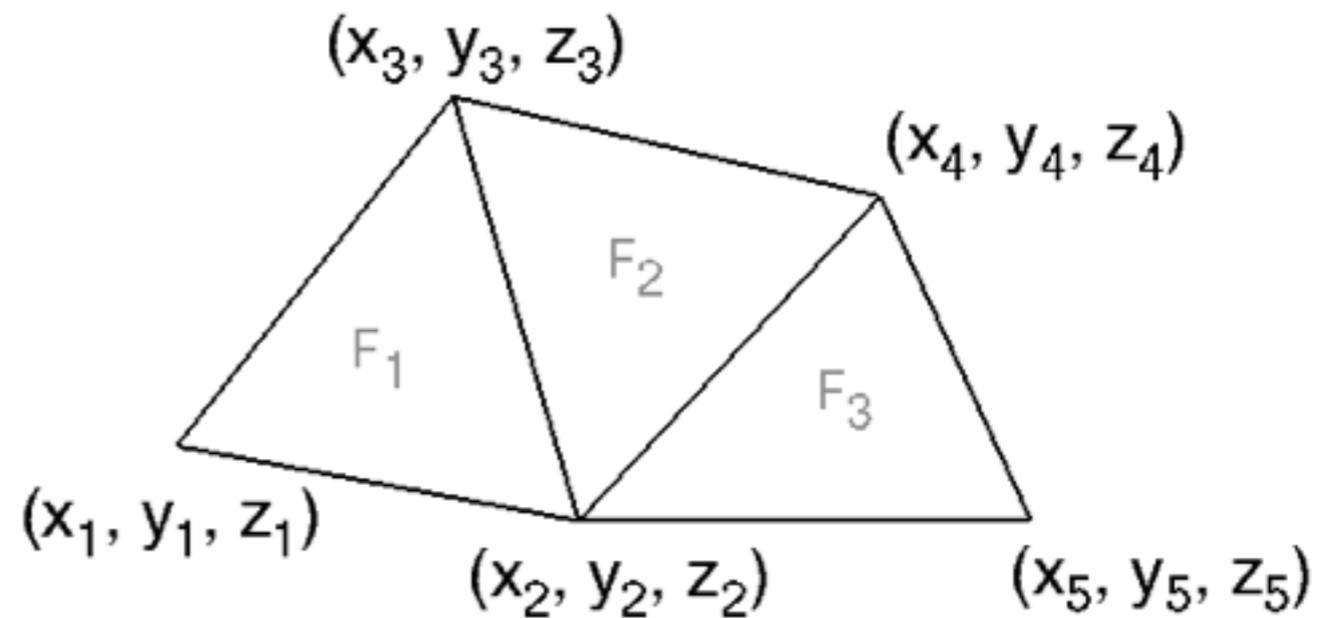
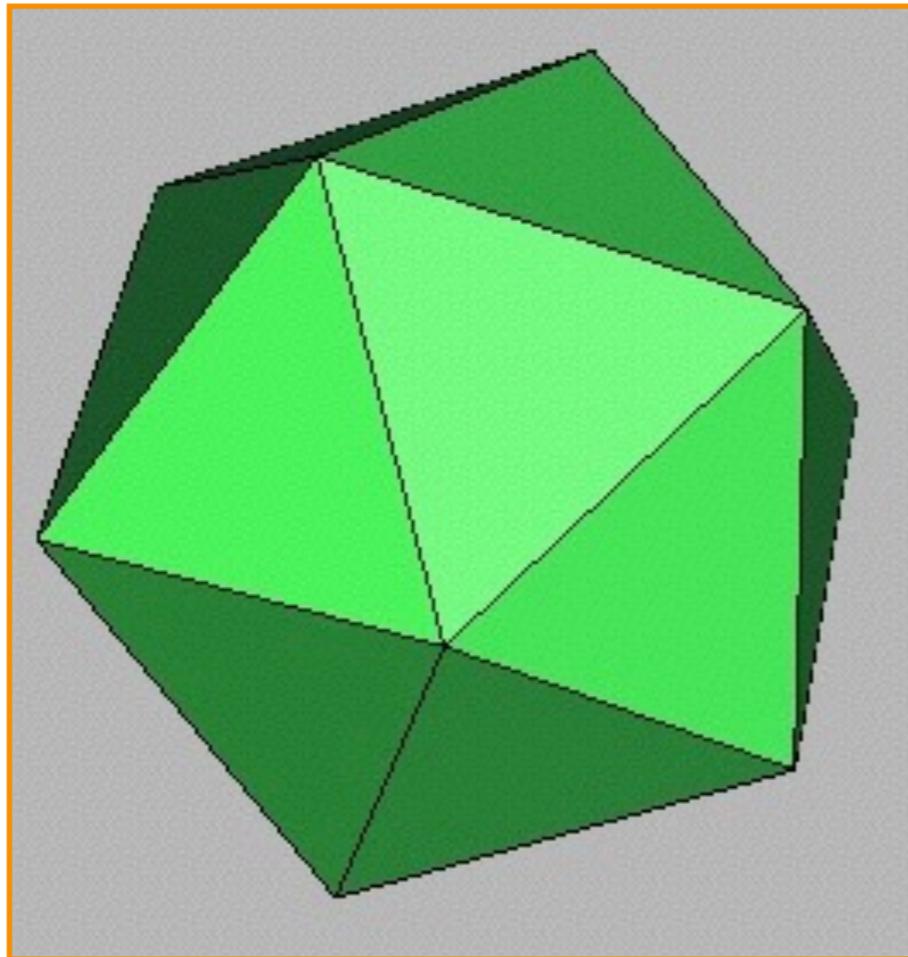


FACE TABLE

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F_2	(x_2, y_2, z_2)	(x_4, y_4, z_4)	(x_3, y_3, z_3)
F_3	(x_2, y_2, z_2)	(x_5, y_5, z_5)	(x_4, y_4, z_4)

Vertex and Face Tables

- Each face lists vertex references

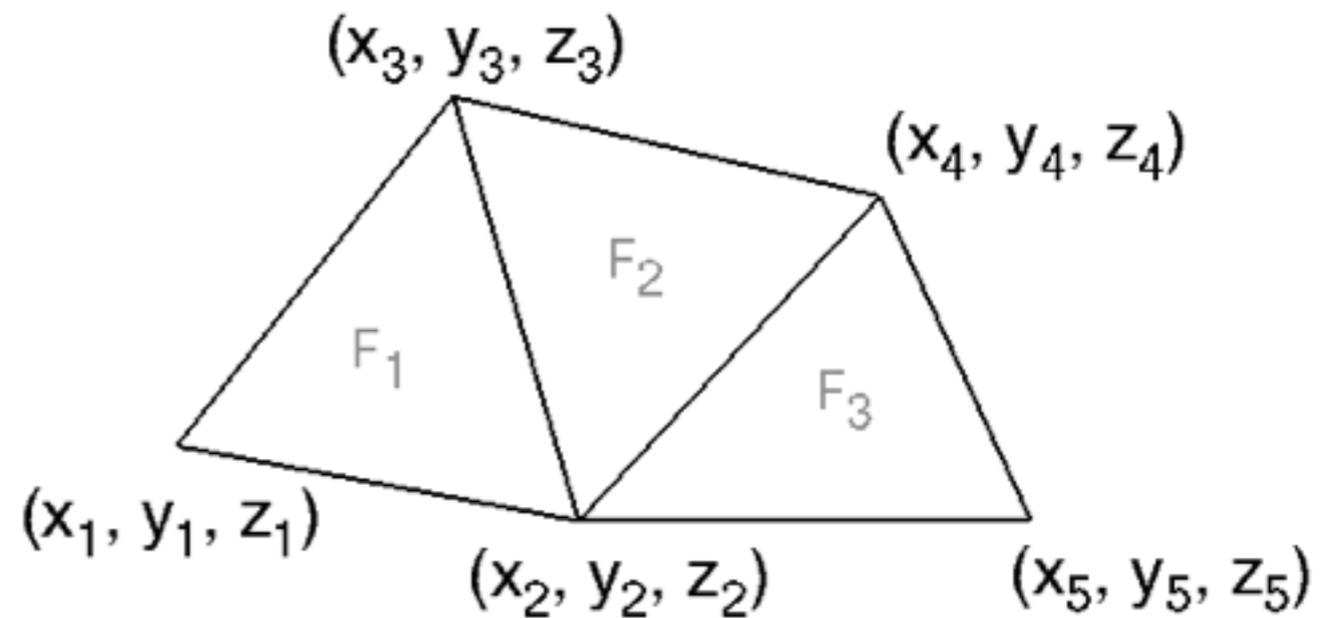
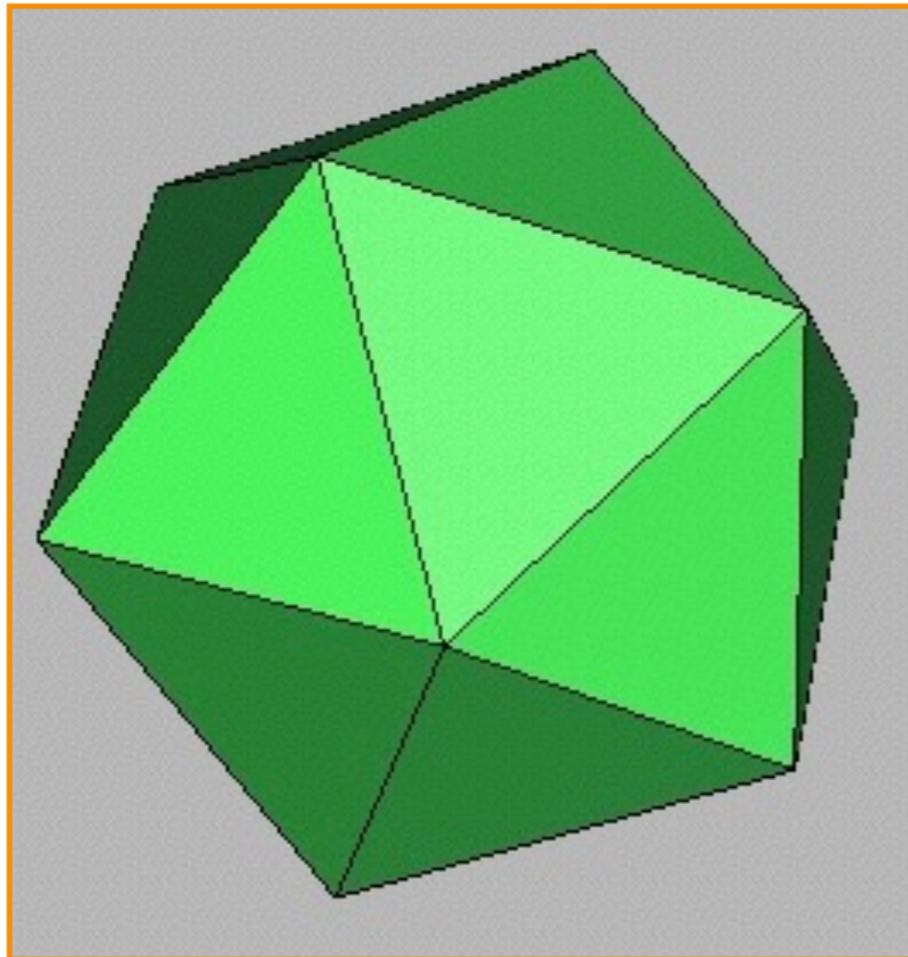


VERTEX TABLE			
V_1	X_1	Y_1	Z_1
V_2	X_2	Y_2	Z_2
V_3	X_3	Y_3	Z_3
V_4	X_4	Y_4	Z_4
V_5	X_5	Y_5	Z_5

FACE TABLE			
F_1	V_1	V_2	V_3
F_2	V_2	V_4	V_3
F_3	V_2	V_5	V_4

Vertex and Face Tables

- Each face lists vertex references
 - ✓ Shared vertices

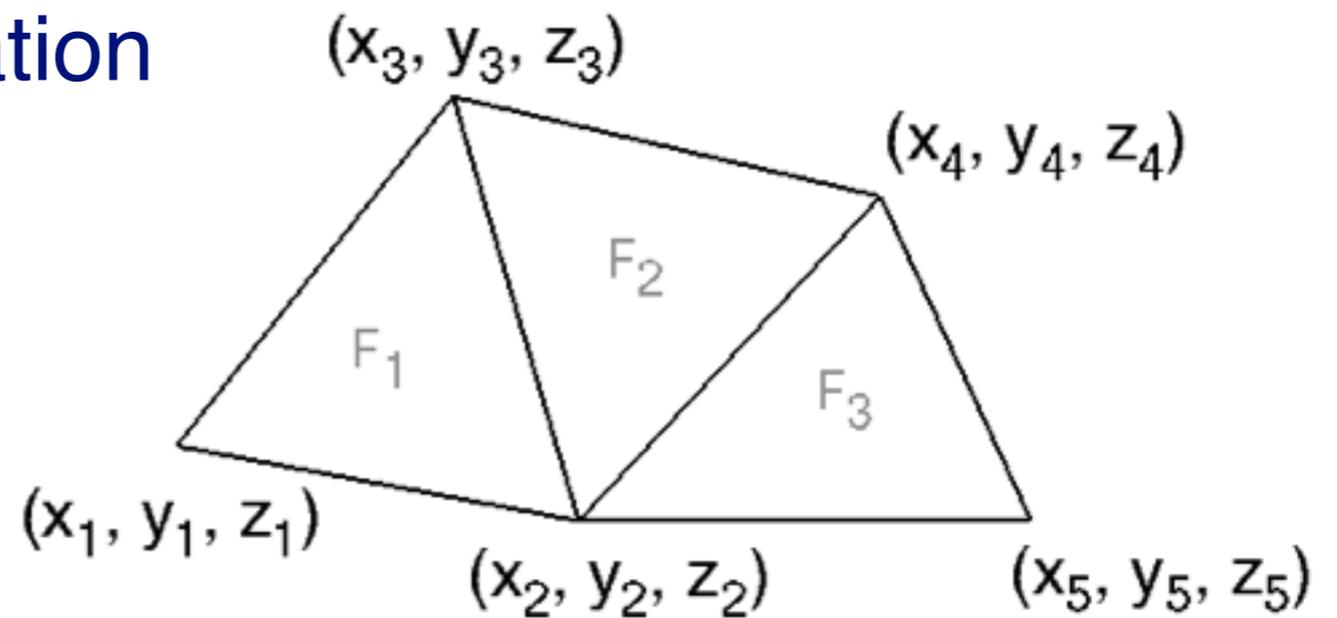
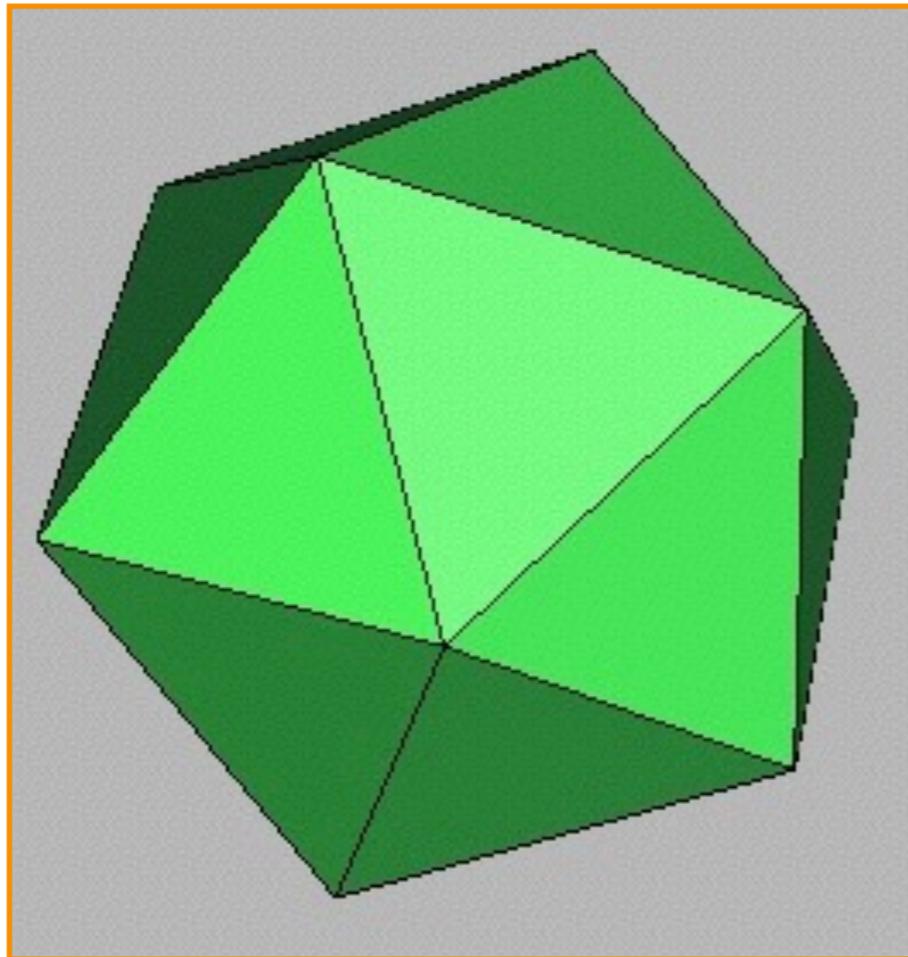


VERTEX TABLE			
V ₁	X ₁	Y ₁	Z ₁
V ₂	X ₂	Y ₂	Z ₂
V ₃	X ₃	Y ₃	Z ₃
V ₄	X ₄	Y ₄	Z ₄
V ₅	X ₅	Y ₅	Z ₅

FACE TABLE			
F ₁	V ₁	V ₂	V ₃
F ₂	V ₂	V ₄	V ₃
F ₃	V ₂	V ₅	V ₄

Vertex and Face Tables

- Each face lists vertex references
 - ✓ Shared vertices
 - ✗ Still no topology information

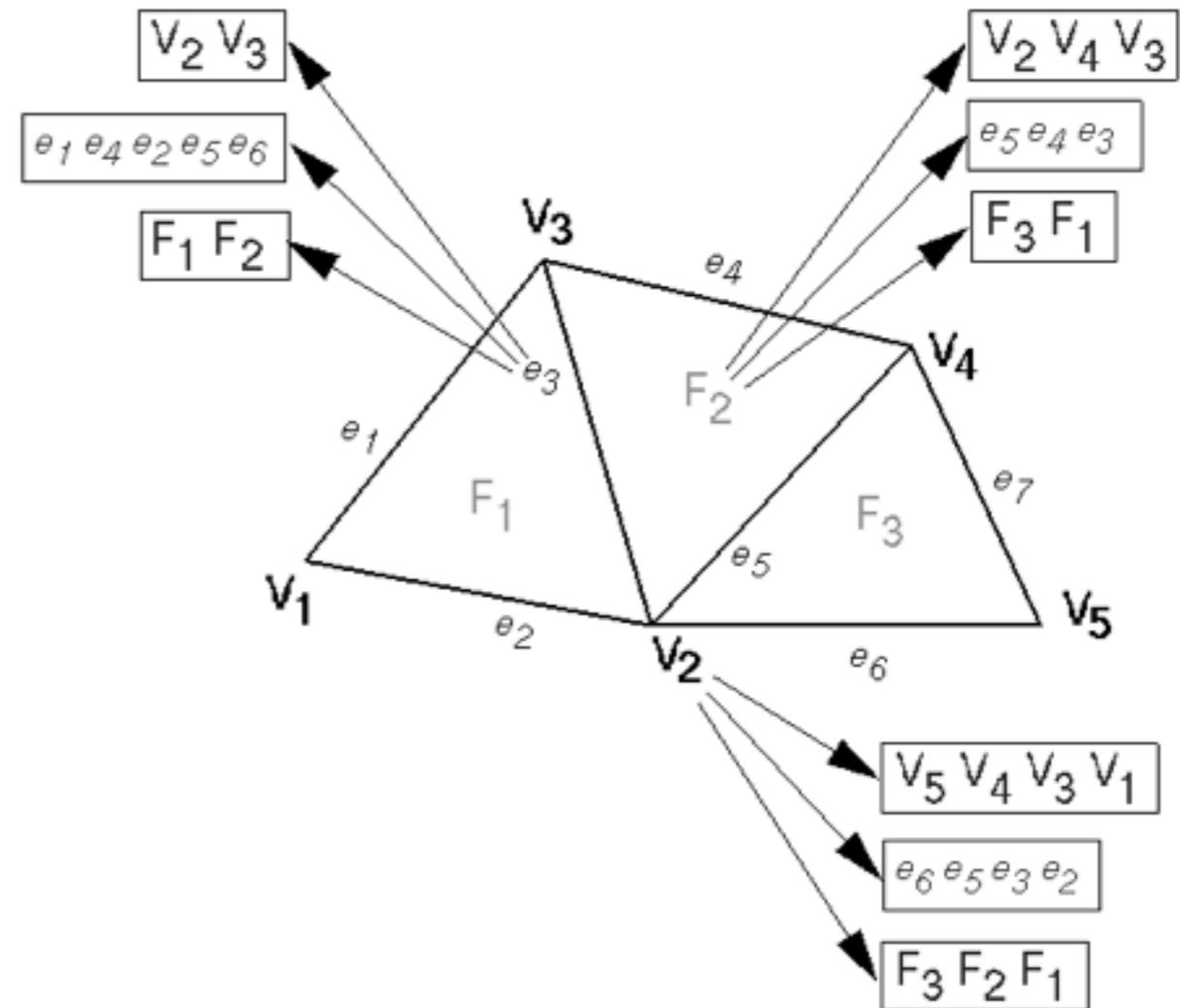
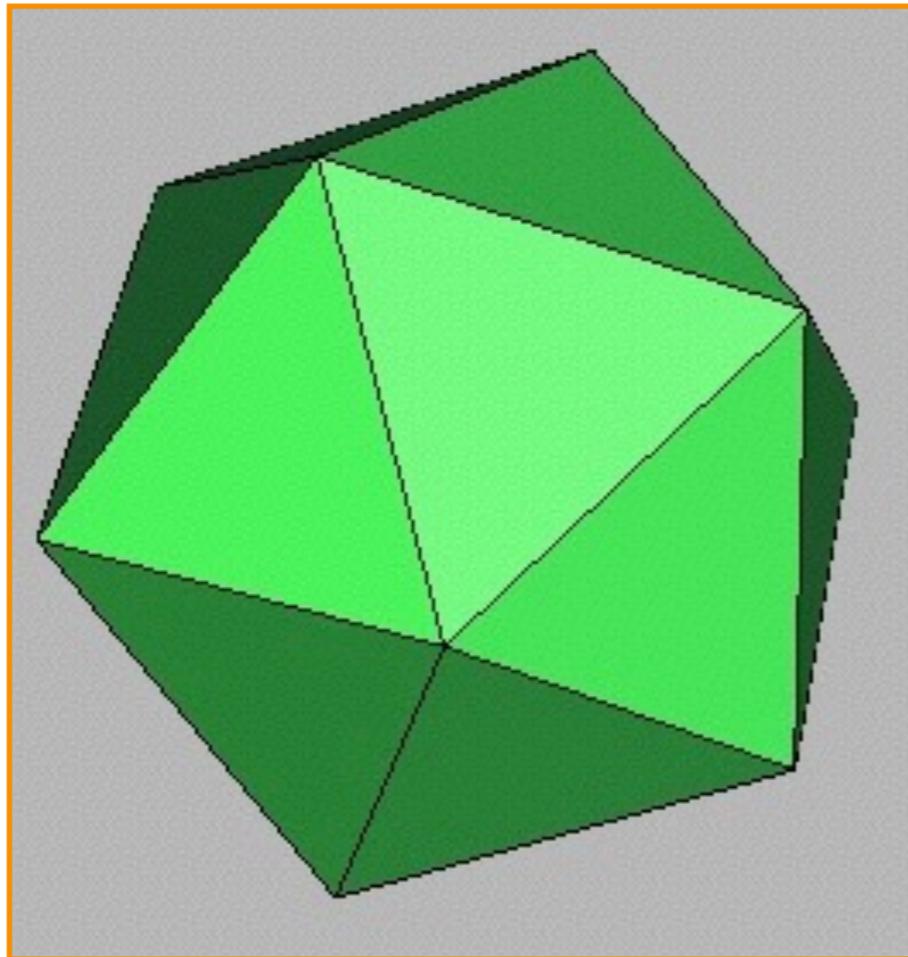


VERTEX TABLE			
V ₁	X ₁	Y ₁	Z ₁
V ₂	X ₂	Y ₂	Z ₂
V ₃	X ₃	Y ₃	Z ₃
V ₄	X ₄	Y ₄	Z ₄
V ₅	X ₅	Y ₅	Z ₅

FACE TABLE			
F ₁	V ₁	V ₂	V ₃
F ₂	V ₂	V ₄	V ₃
F ₃	V ₂	V ₅	V ₄

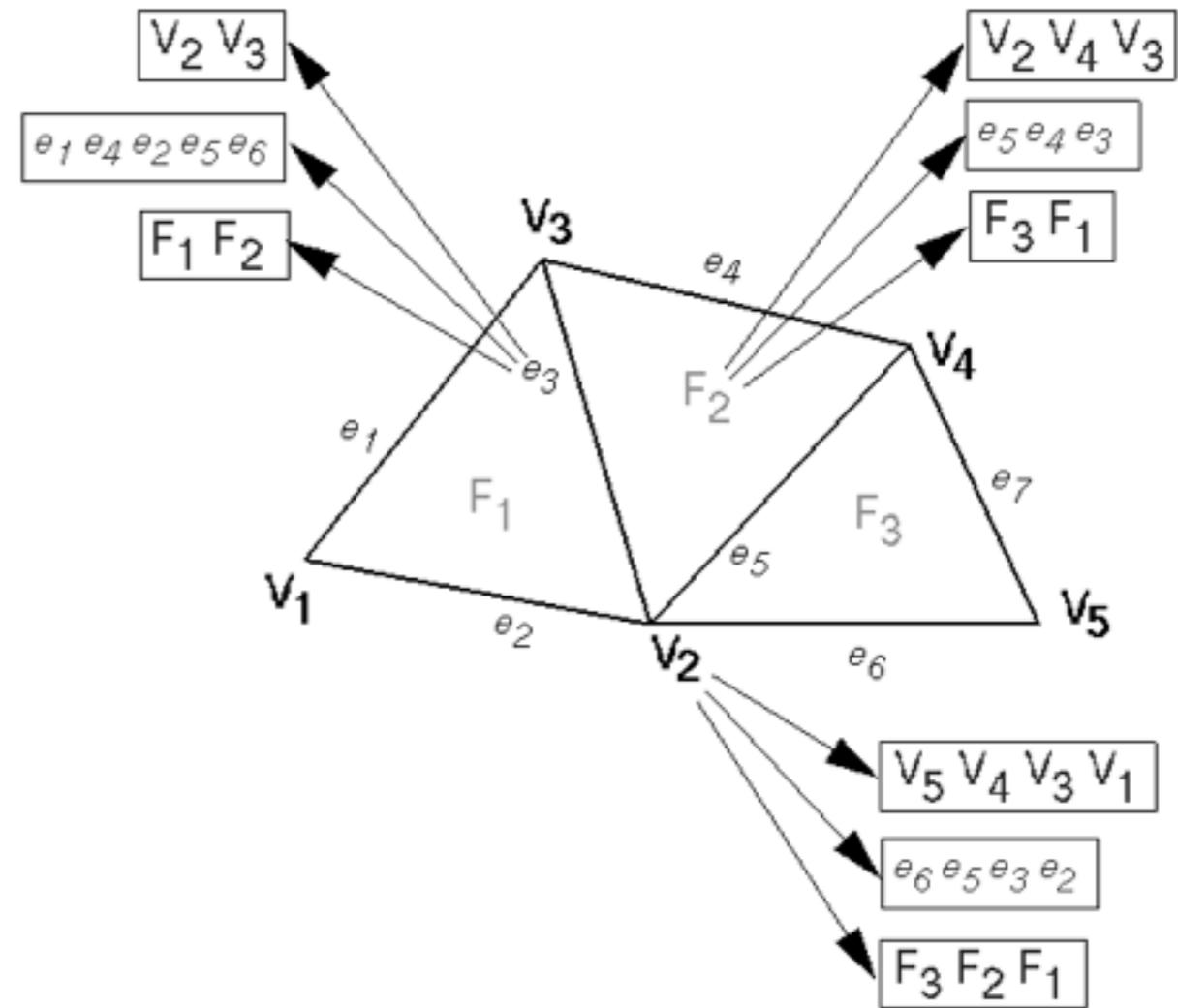
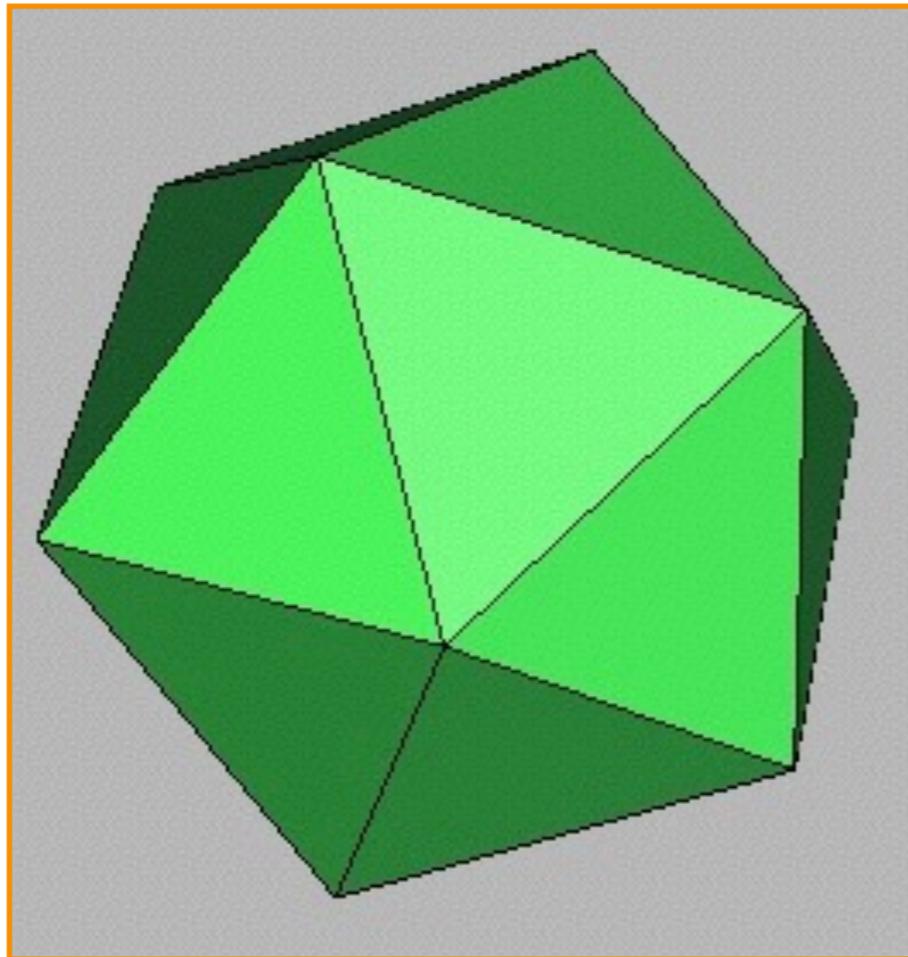
Adjacency Lists

- Store all vertex, edge, and face adjacencies



Adjacency Lists

- Store all vertex, edge, and face adjacencies
 - ✓ Efficient topology traversal



Adjacency Lists

- Store all vertex, edge, and face adjacencies
 - ✓ Efficient topology traversal
 - ✗ Extra storage
 - ✗ Variable size arrays

